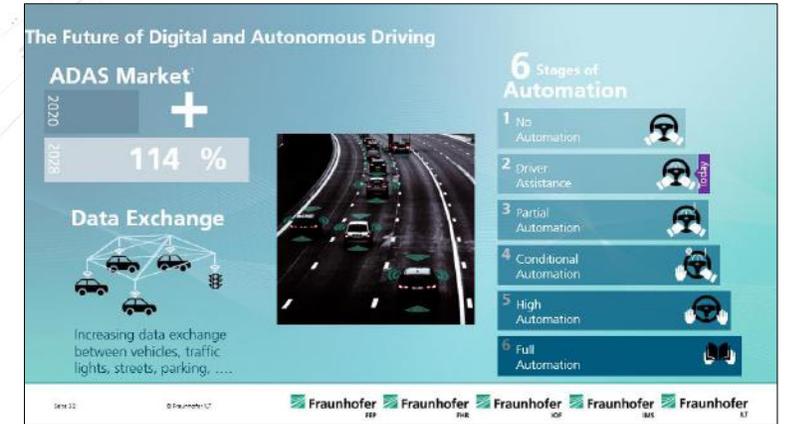
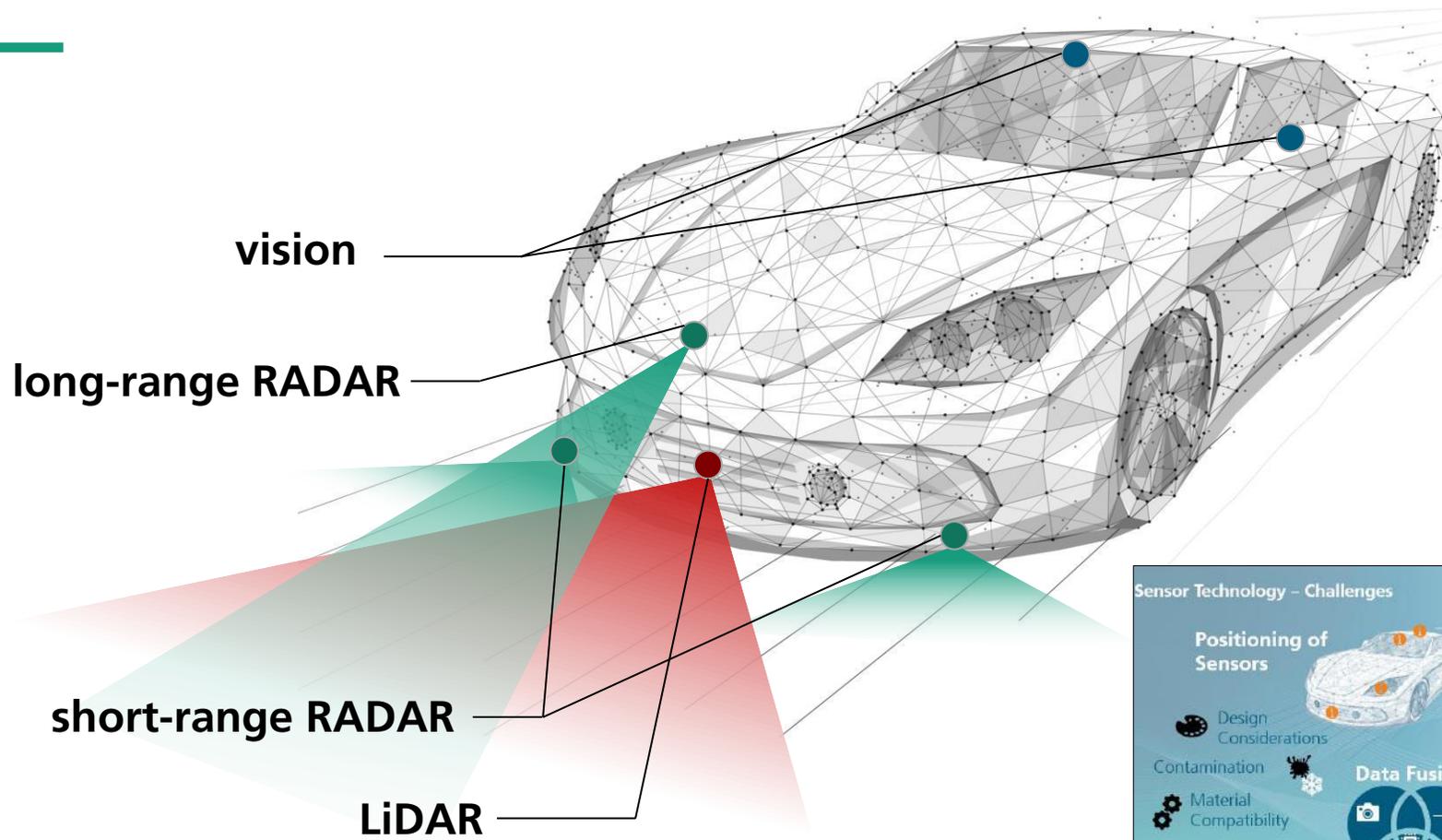




Coaxial RADAR, LiDAR and Light Integration in Smart Headlights

SMART HEADLIGHT

State of the Art



Sensor Technology - Challenges

Positioning of Sensors

Design Considerations

- Contamination
- Material Compatibility

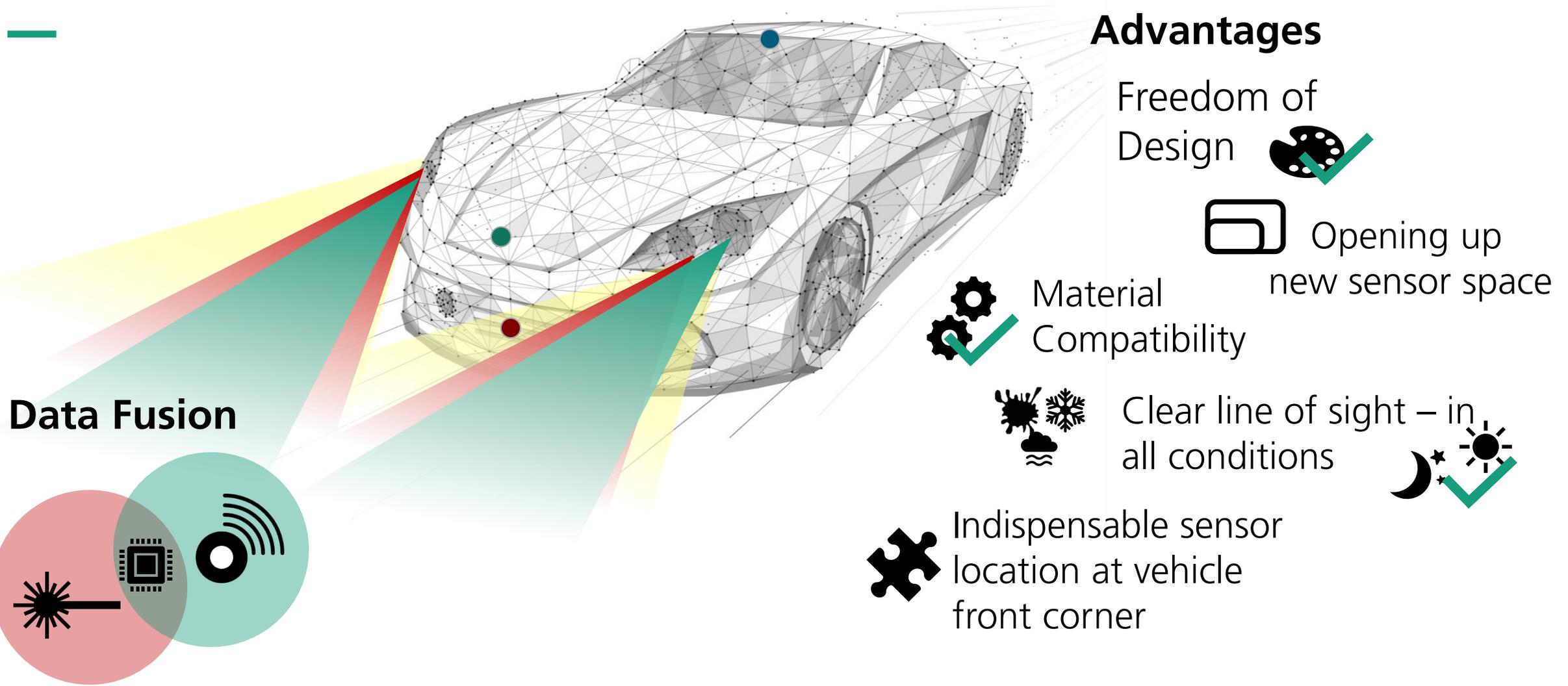
Data Fusion

Sensor Capabilities

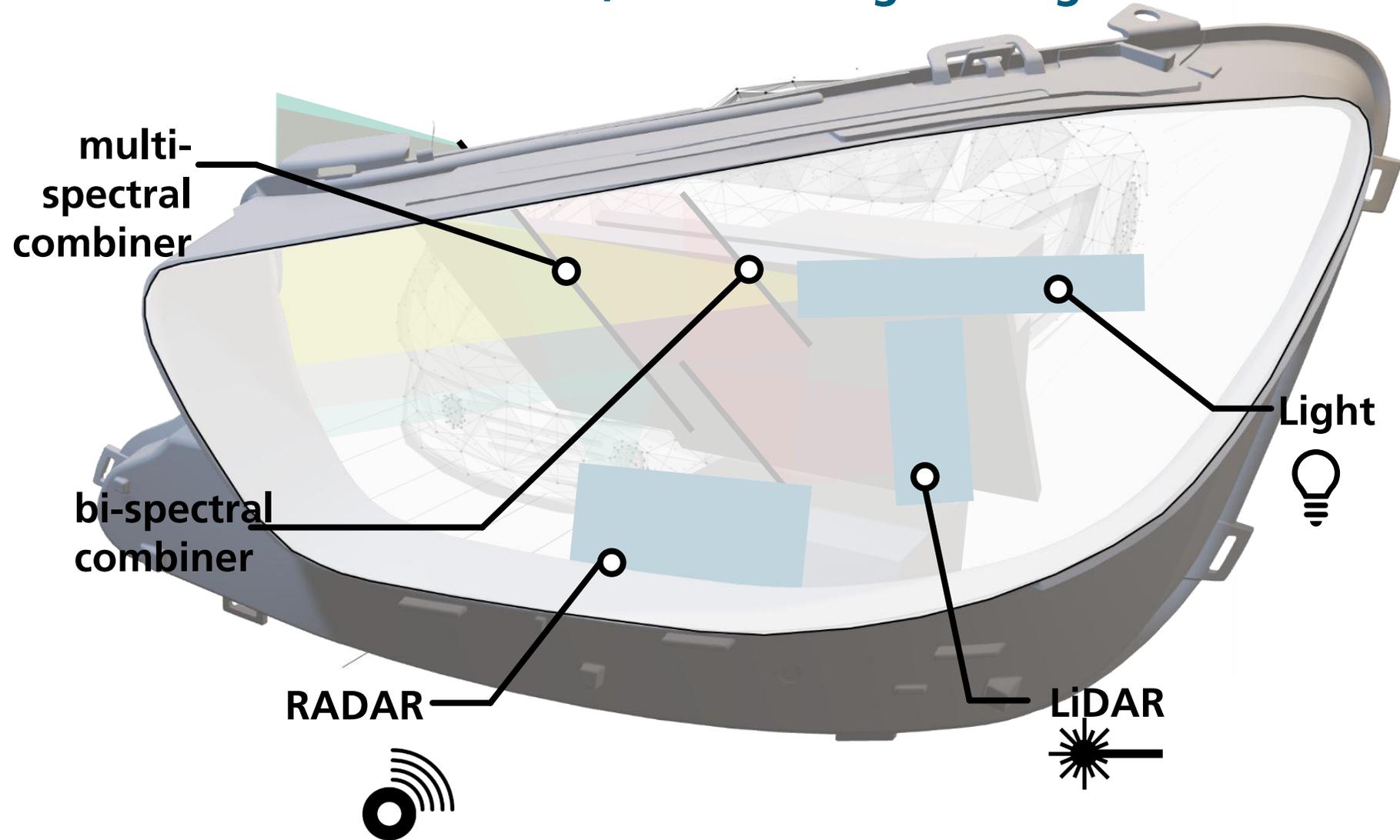
	Vision	RADAR	LiDAR
Range	-	+	o
Resolution	+	-	+
3D capability	o	-	+
Object speed detection	-	+	o
Read signs / colors	+	-	-
Immune to weather	-	+	o
Works in dark	-	+	+
Works in bright sun	o	+	o
Interference effects	o	+	o

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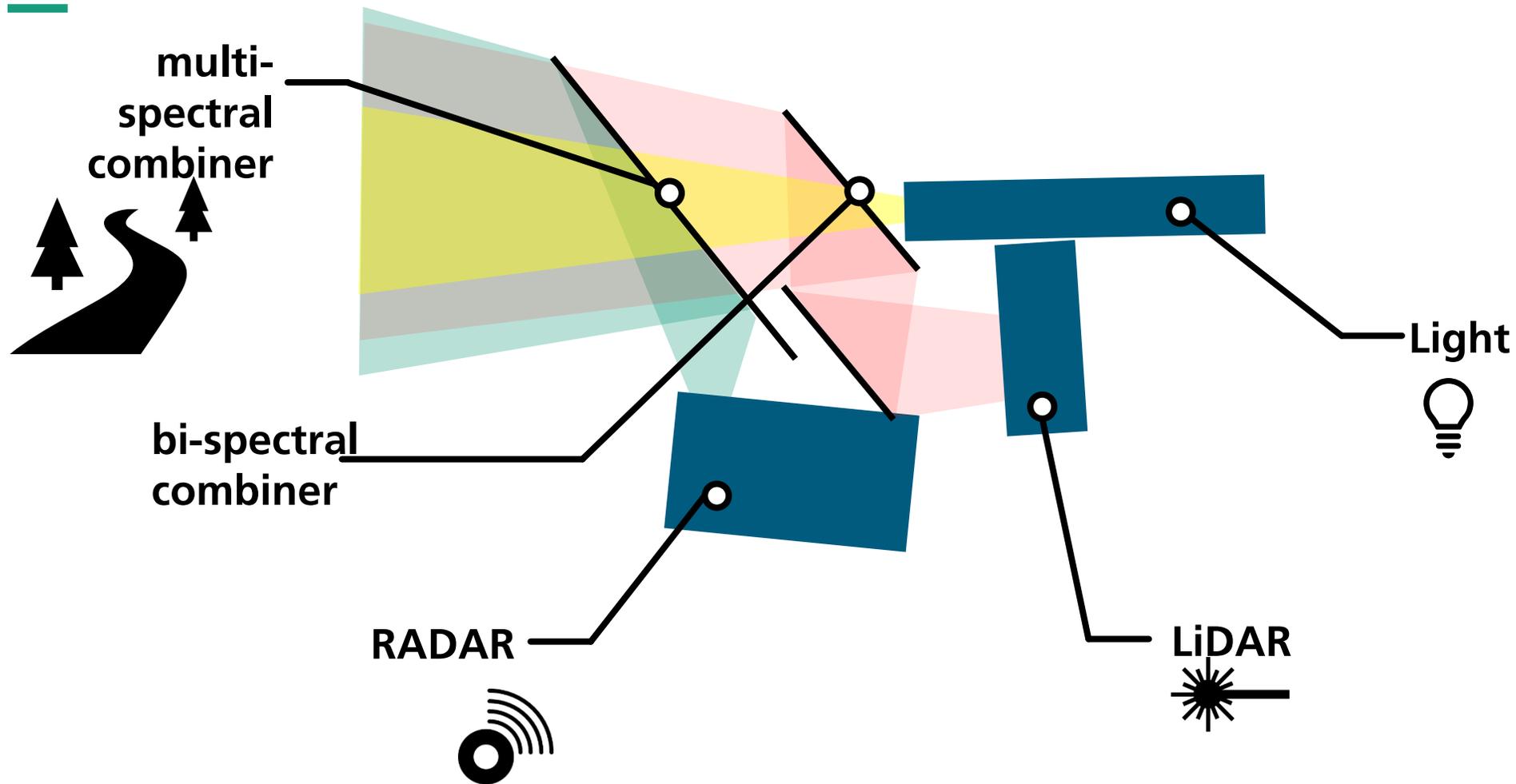
Our Solution: Coaxial RADAR, LiDAR & Light Integration in Smart Headlights

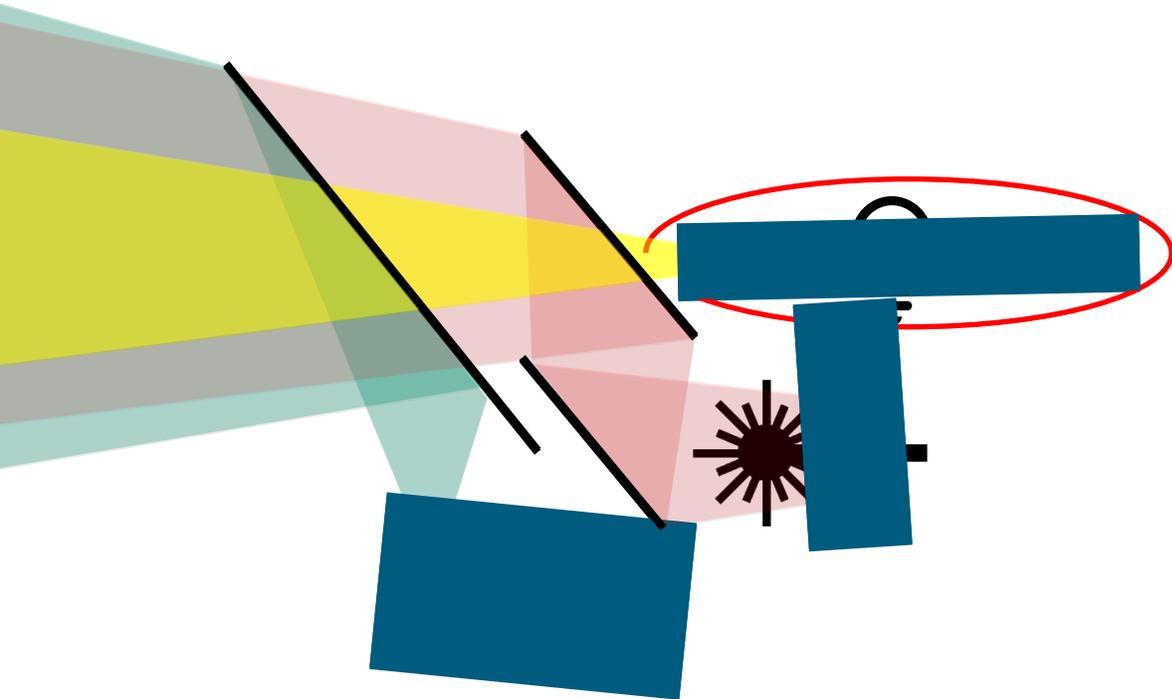


Our Solution: Coaxial RADAR, LiDAR & Light Integration in Smart Headlights



Our Solution: Coaxial RADAR, LiDAR & Light Integration in Smart Headlights





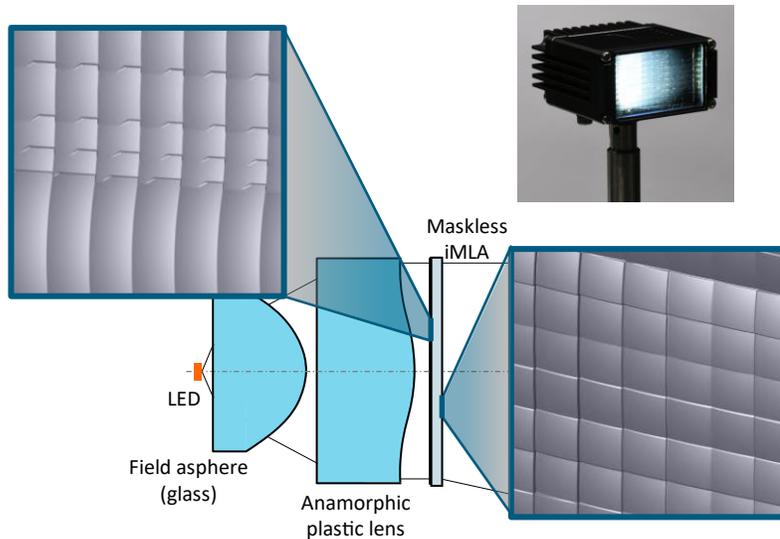
Lighting – a Micro-Optical Approach

Lighting – a Micro-Optical Approach

Low Beam

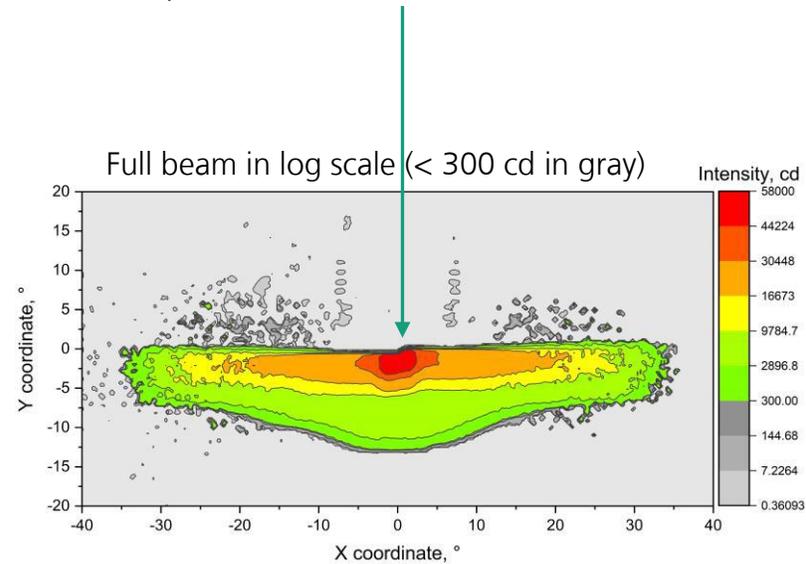
Design

- + Completely **maskless** MLAs on both sides
- + Simpler collimator architecture possible
- + Size reduction → room for sensors



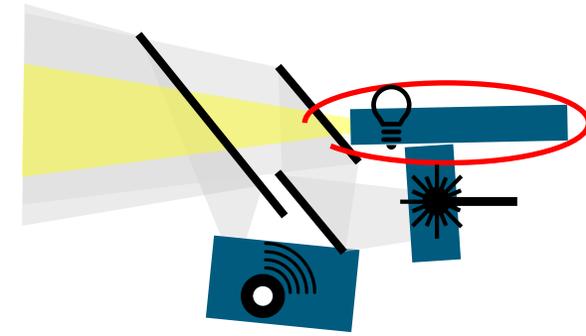
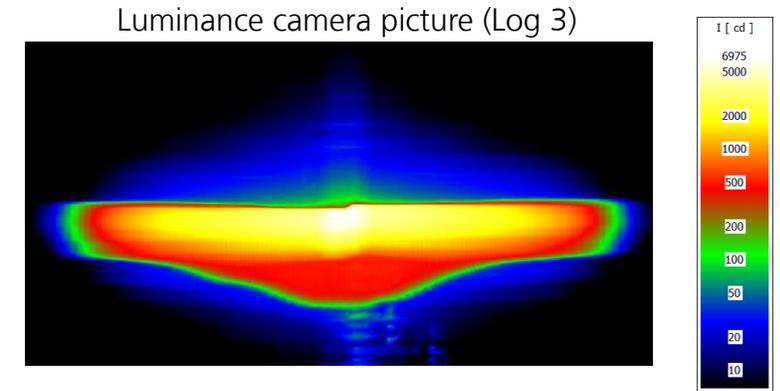
Simulation

- FOV $\pm 35^\circ$ horizontal (~ 625 cd); $-12^\circ \dots 0^\circ$ vertical
- Asymmetric and steep cut-off (in compliance with ECE standard)



Measurement

- Up to ~ 10.5 kcd / module → **42_{kcd} total**
- Sharp cut-off, no color
- **75%** total transmission
- **.91%** MLA transmission (uncoated)

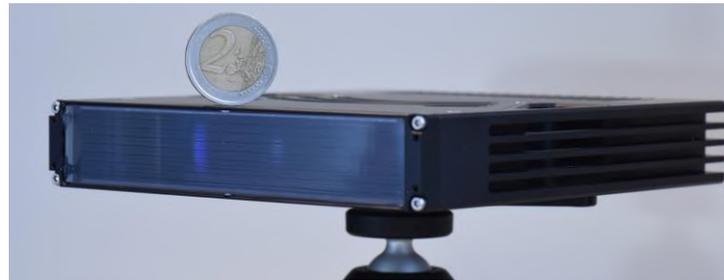
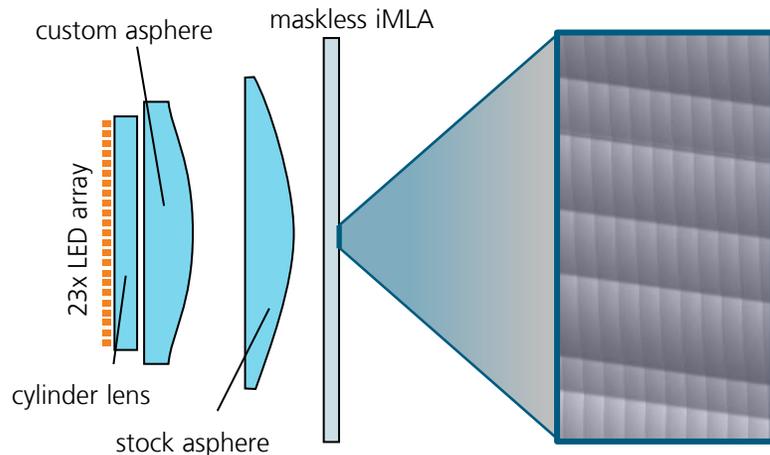


Lighting – a Micro-Optical Approach

High Beam

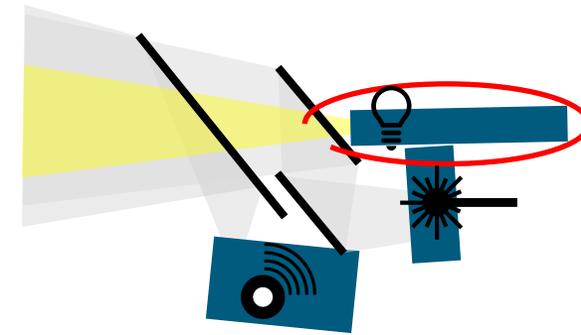
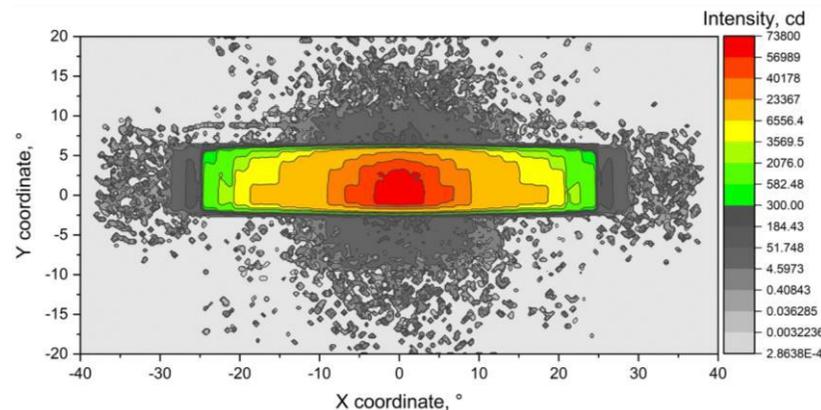
Design

- + Completely **maskless** MLAs, irregular in vertical, regular in horizontal
- + Size reduction → room for sensors
- + 21 switchable dark tunnels of 2° are achieved



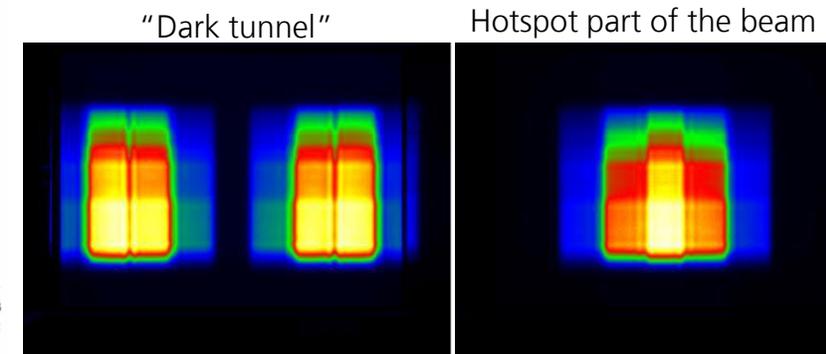
Simulation

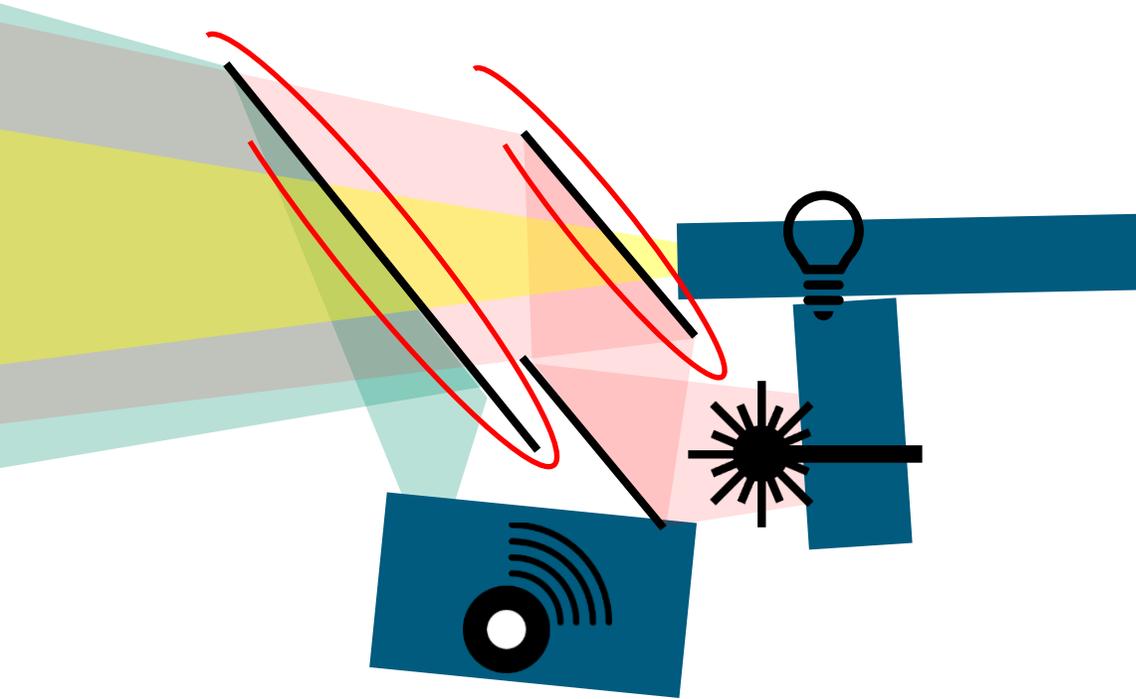
- MLA transmission → > 90%
- Efficiency (AR coated colli) ~ 40%. Limit → Etendue @ Colli



Measurement

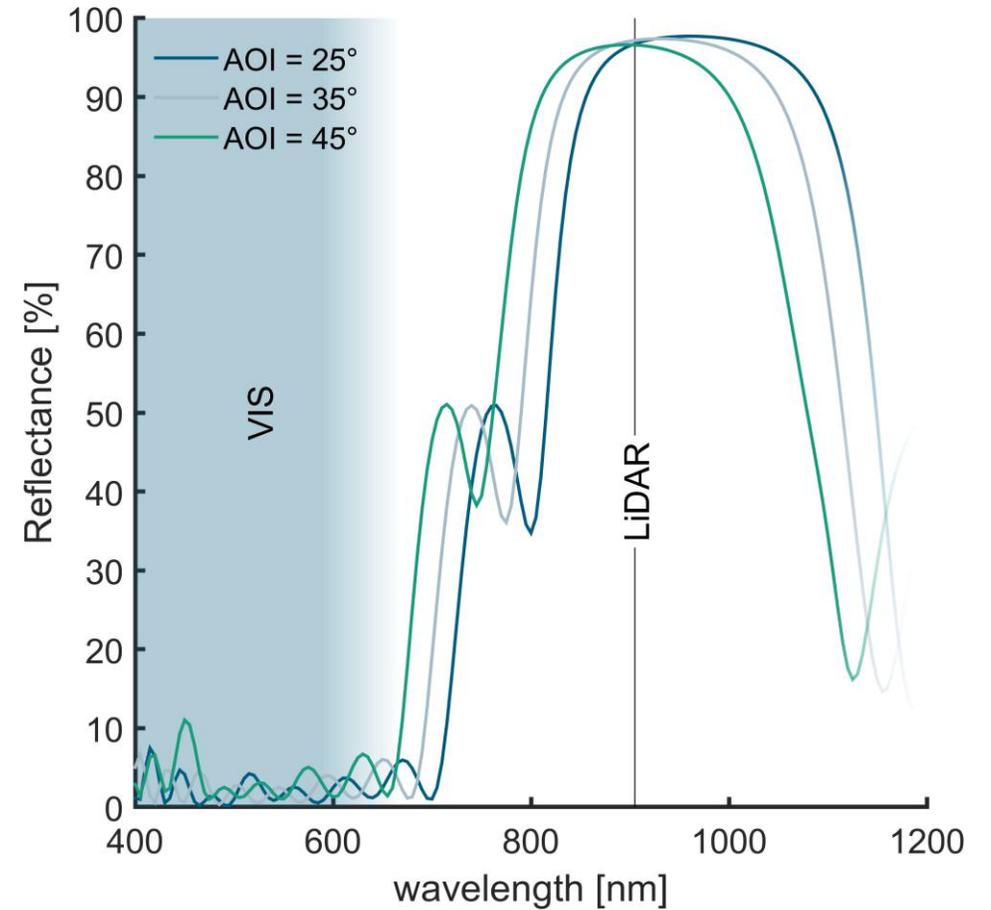
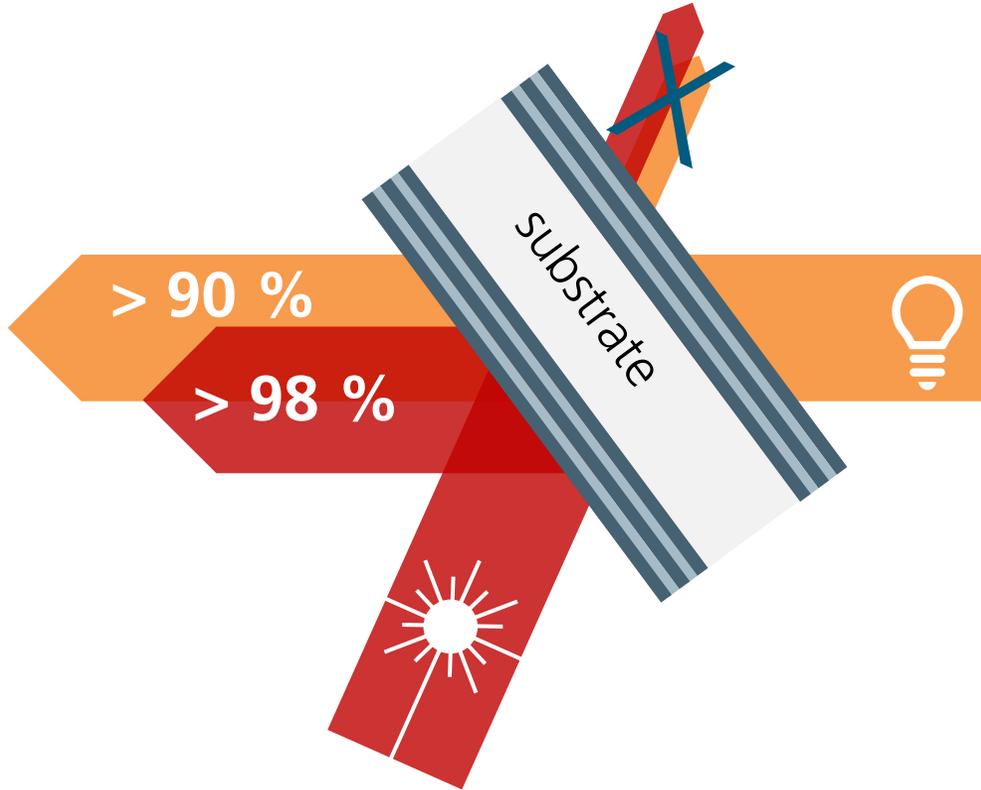
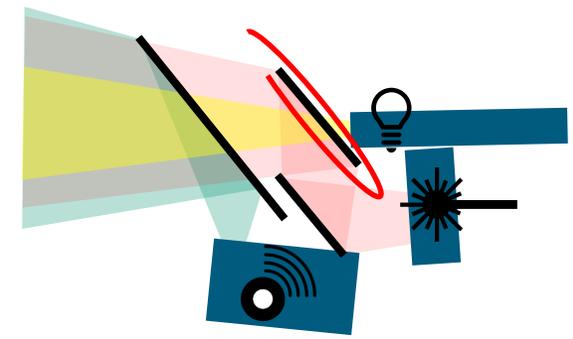
- ~ **100** kcd with 2 modules (585 lm LED)
- Sharp “dark tunnels” of 2° full width
- **40%** total transmission
- **91%** MLA transmission (uncoated)



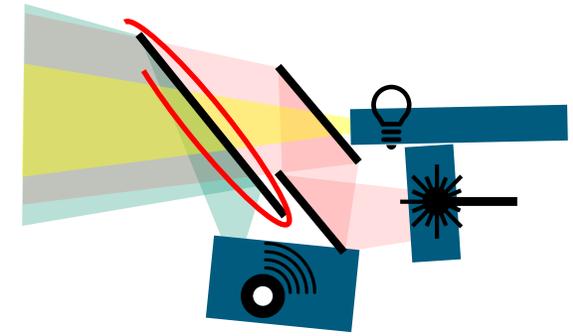
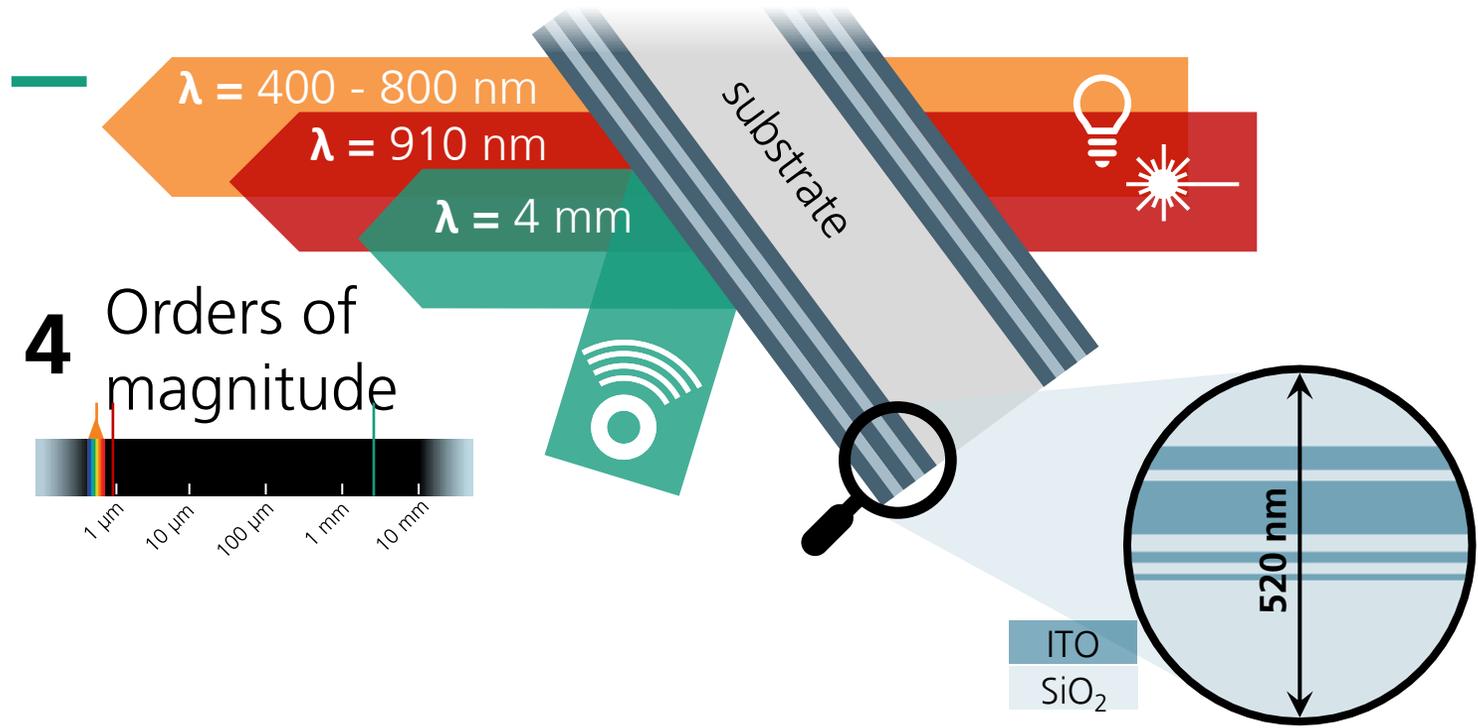


Combiner

Combining Light and Lidar: Bi-Spectral Combiner



Everything comes together: Multi-Spectral Combiner

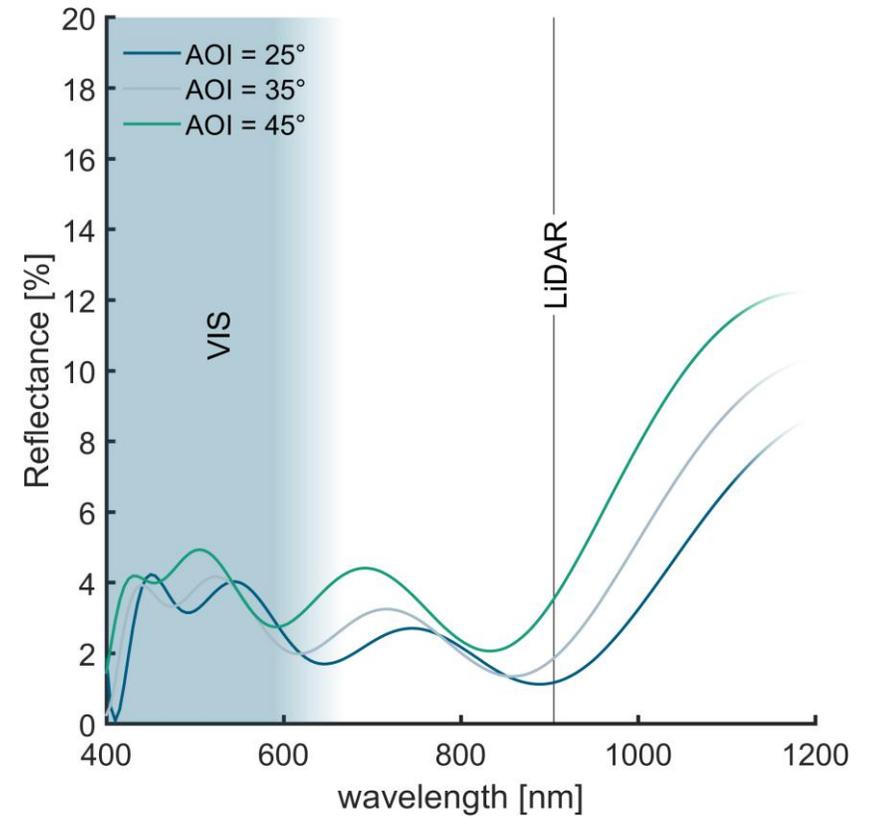


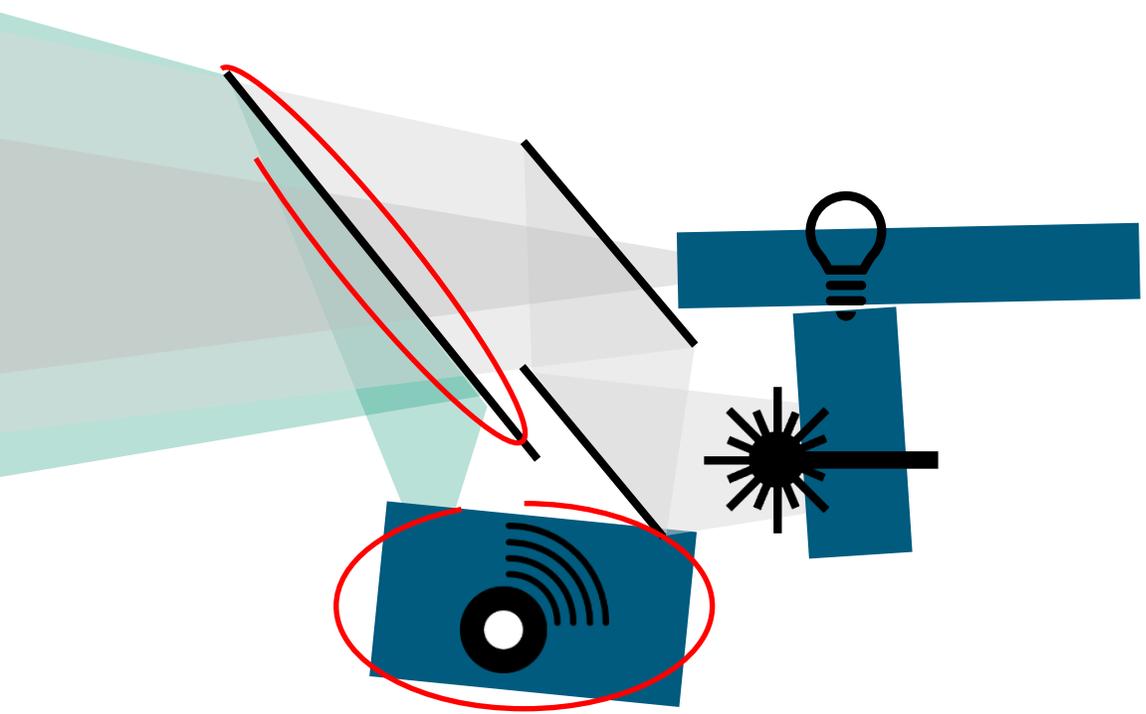
ITO

transparent & conductive →
use as high refractive index material in AR coating

< 5%

reflection losses for Lidar and Light





Multi-Spectral Combiner & RADAR

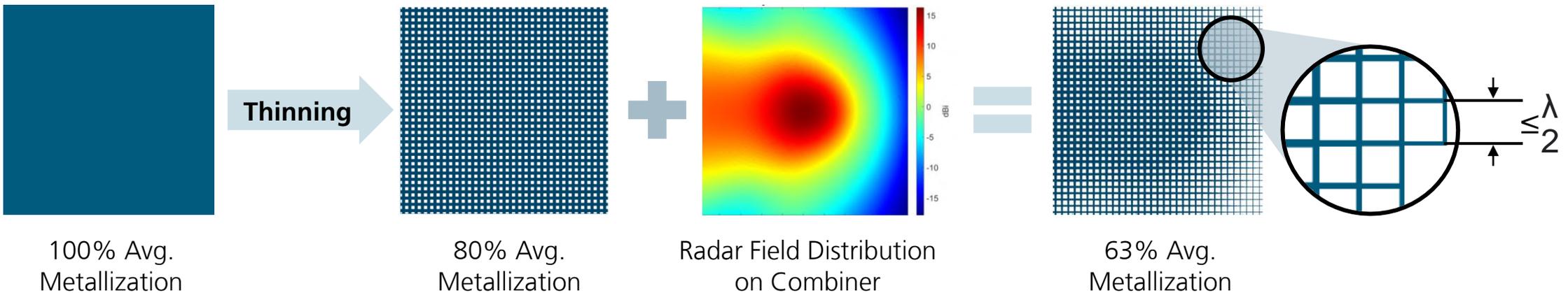
Multi-Spectral Combiner & RADAR

Specular Reflector

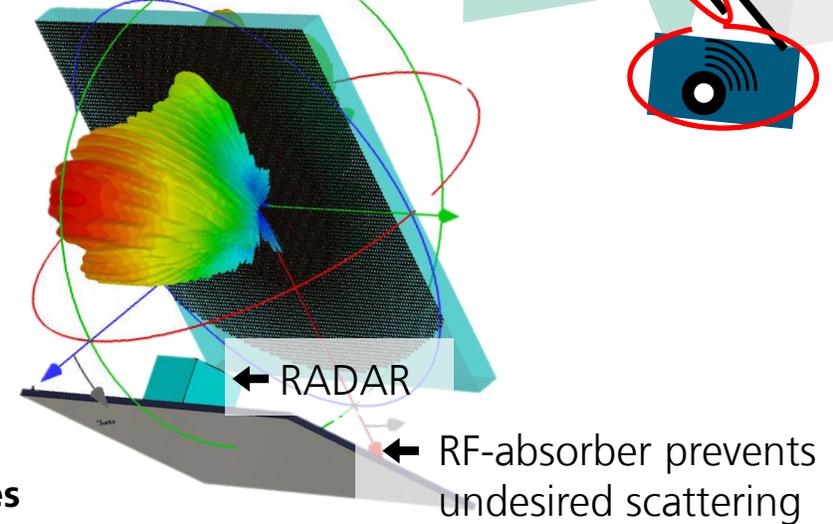
- + No change to radiation pattern of radar
- + High bandwidth
- + Only single sided metallization of combiner is necessary
→ increased optical transmission

→ Design goal:  metallization  light transmission  radar losses

→ Our Approach: Metallization reduction by adaptive patterning

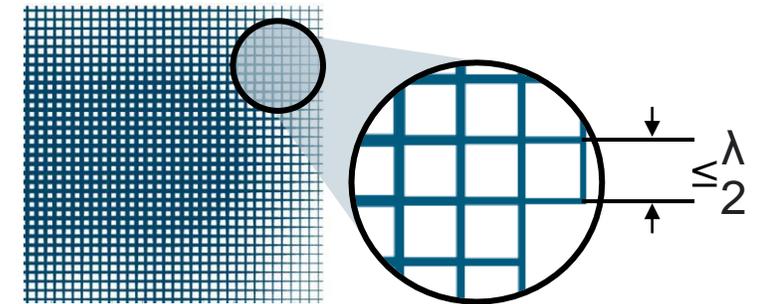
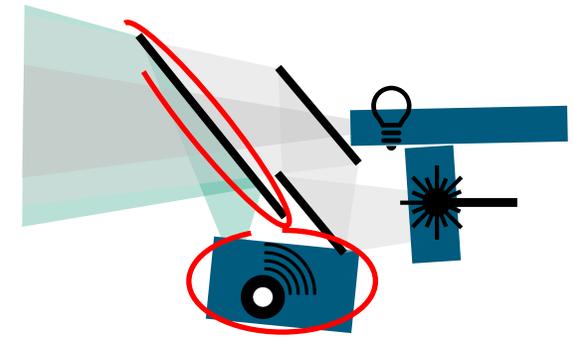
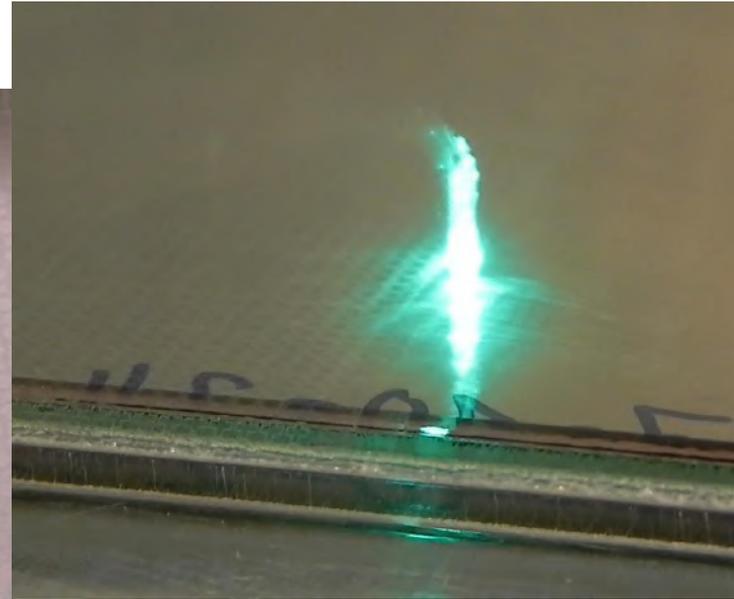
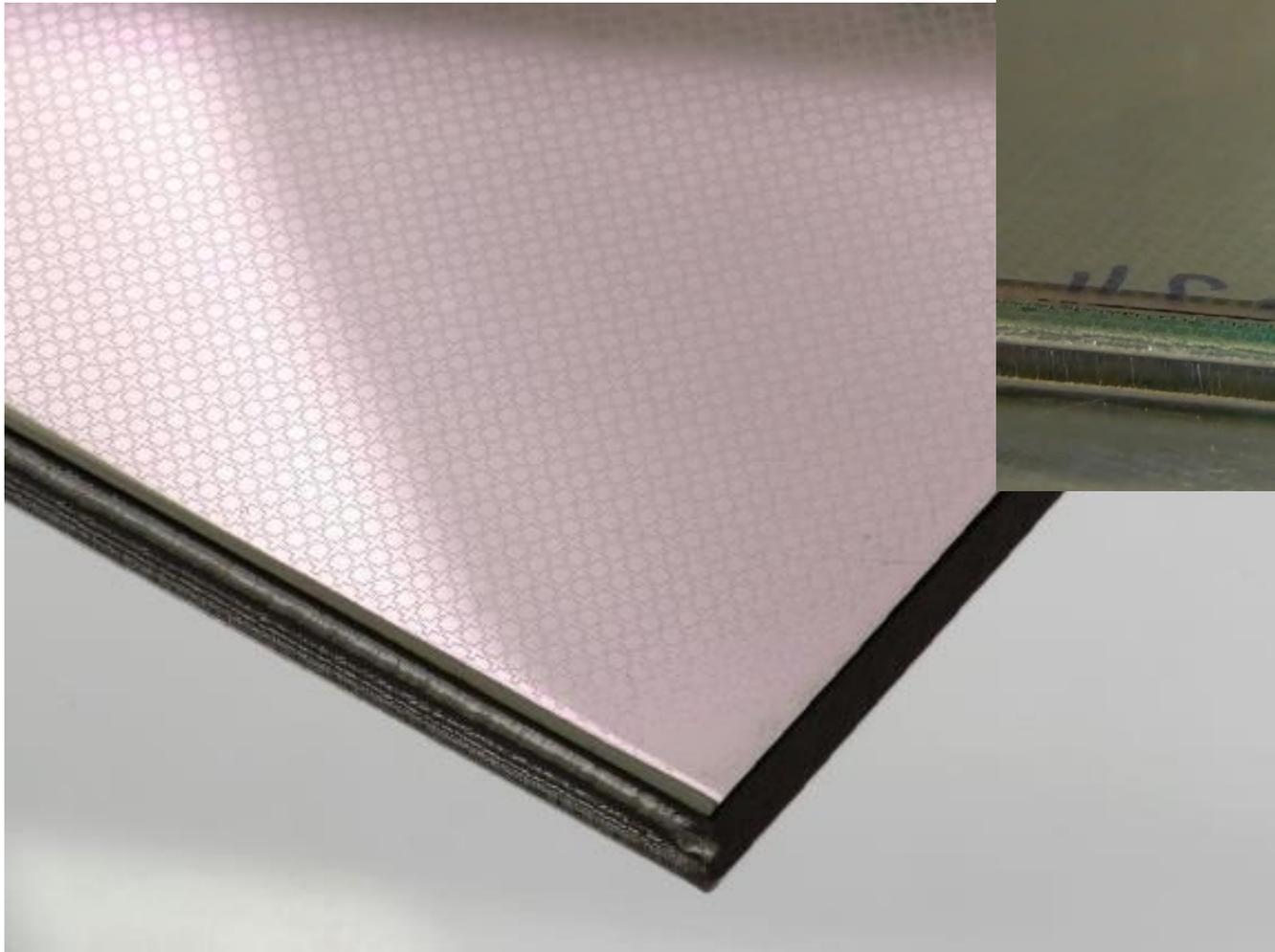


Radiation Pattern at 78.0 GHz



Multi-Spectral Combiner & RADAR

Specular Reflector

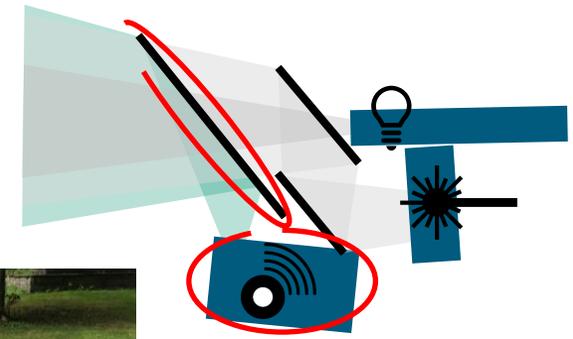
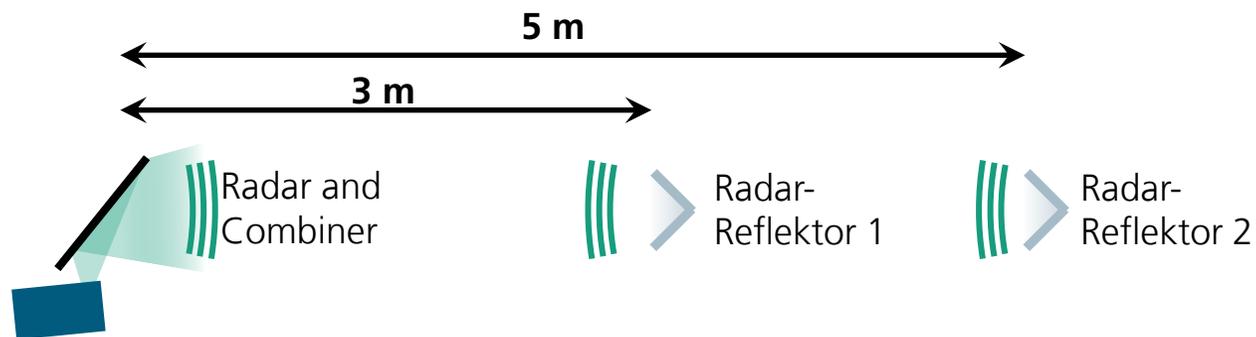


63% Avg.
Metallization

Multi-Spectral Combiner & RADAR

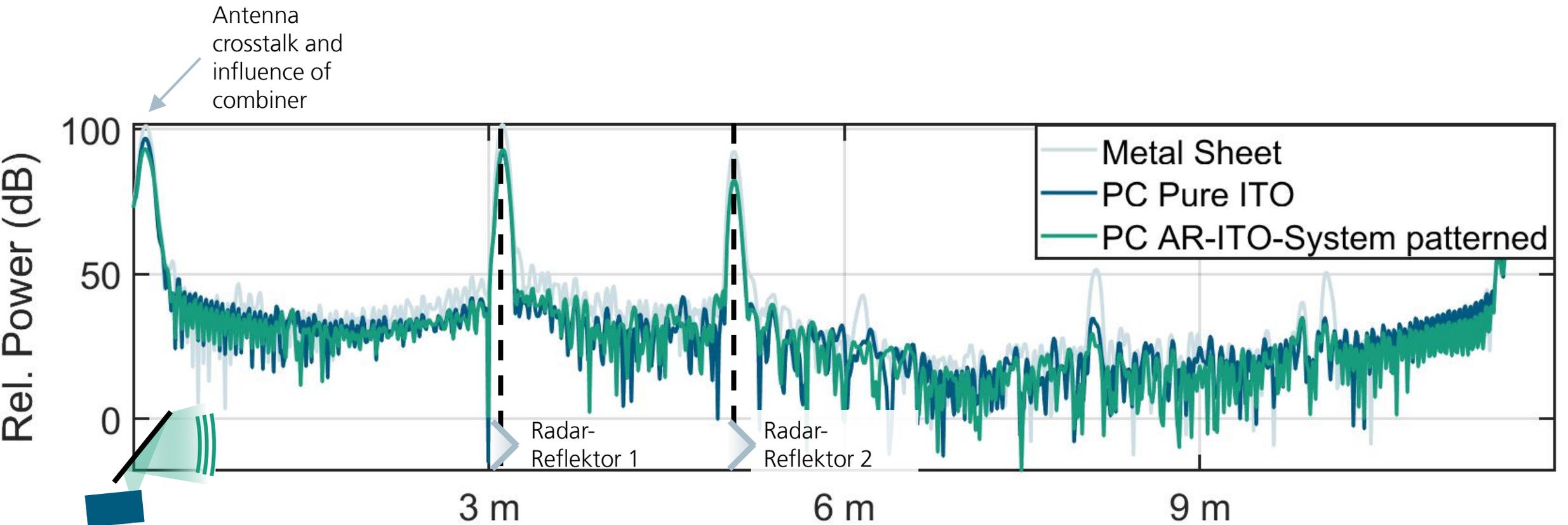
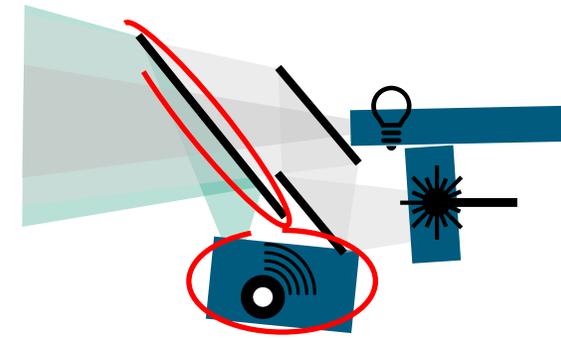
Specular Reflector

- Radar sensor: Texas Instruments AWR1843BOOST Evaluation Board
- All samples 10x10 cm² PC with conductive ITO coating on Radar-facing side
- Targets: Two retro-reflectors (trihedrals) in 3 m and 5 m distance
- 1D-measurement (range profile) of distance to target performed for each sample



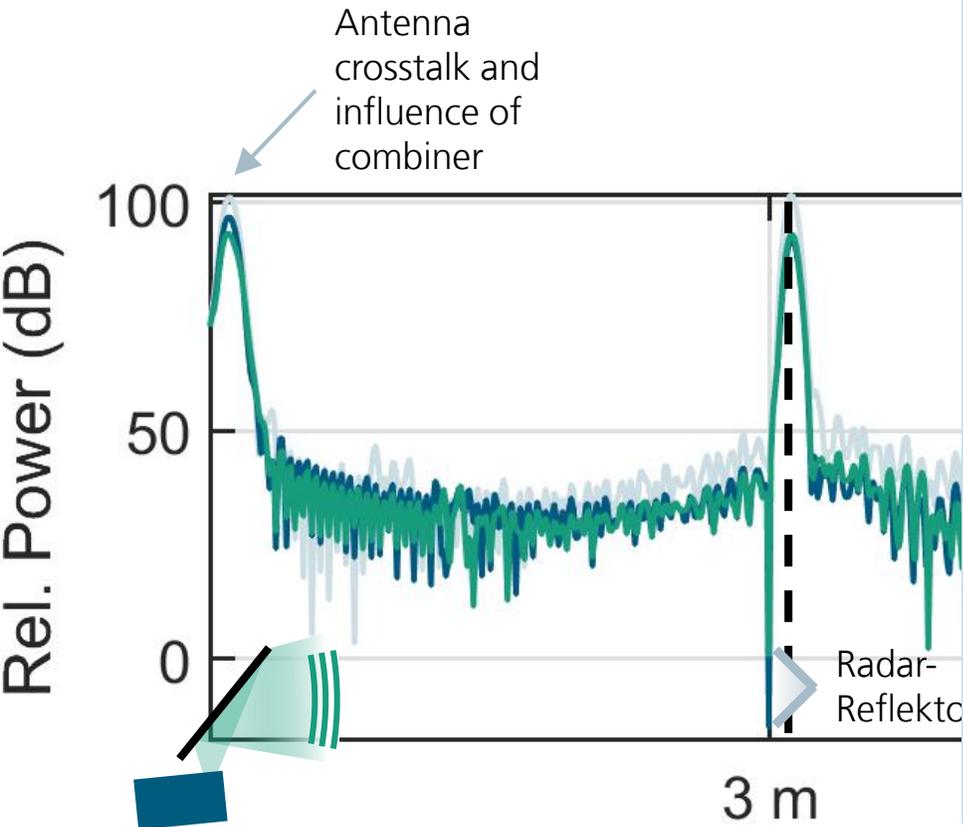
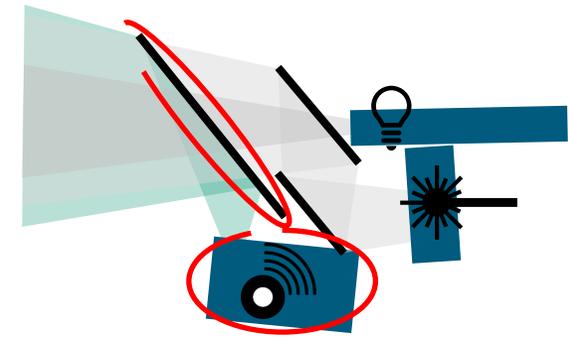
Multi-Spectral Combiner & RADAR

Specular Reflector



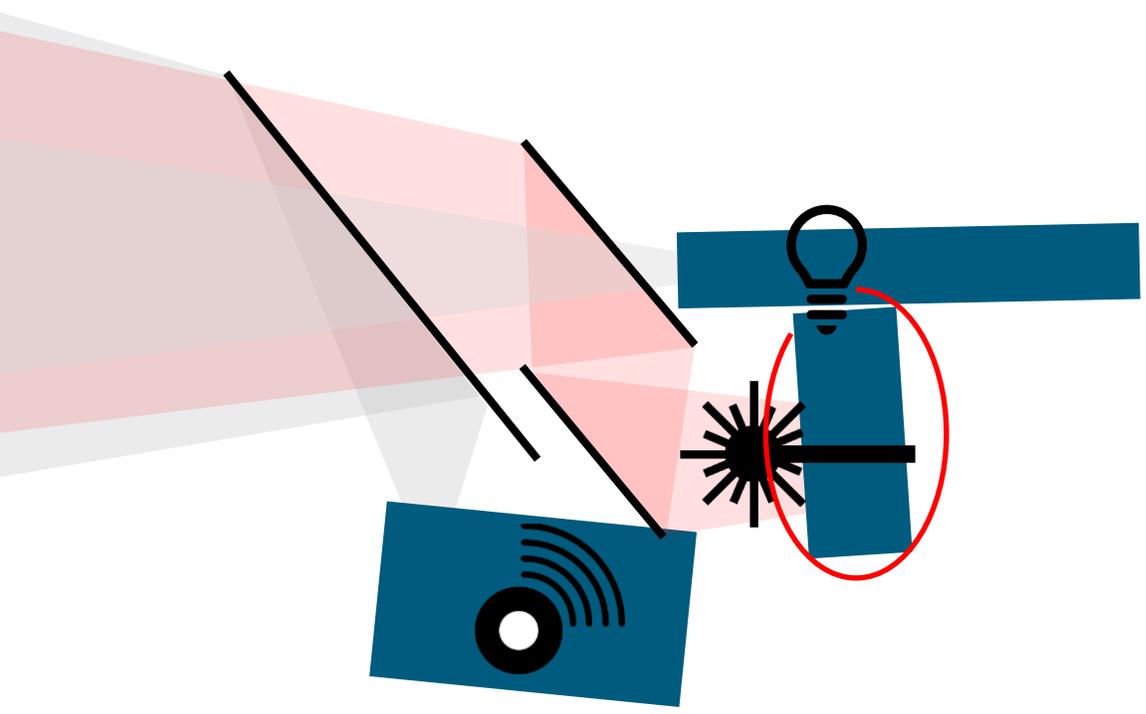
Multi-Spectral Combiner & RADAR

Specular Reflector



- Functionality of optically transparent radar reflector demonstrated successfully
- Reduced electrical conductivity of ITO causes losses
- 3 dB difference in signal strength between fully coated and structured combiner
 - Translates to approx. 15% reduction in max. achievable range
- 7 dB difference in signal strength between best combiner and metal sheet
 - Translates to approx. 33% reduction in max. achievable range



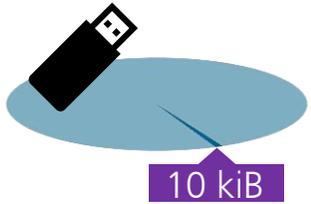


LiDAR

LiDAR

Efficient Algorithm

for direct Time-of-Flight analysis



0.5 %
of previous
memory needed

144fps



x 10 faster
than today

Interference Supression

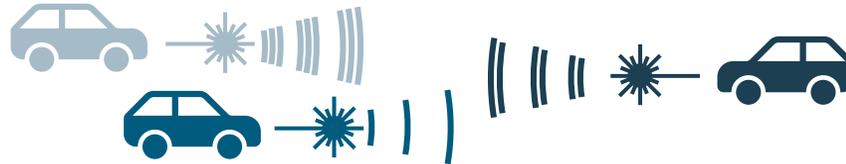
+ LiDAR Signal is individually encoded with random numbers in order to avoid interference with other LiDAR emitters



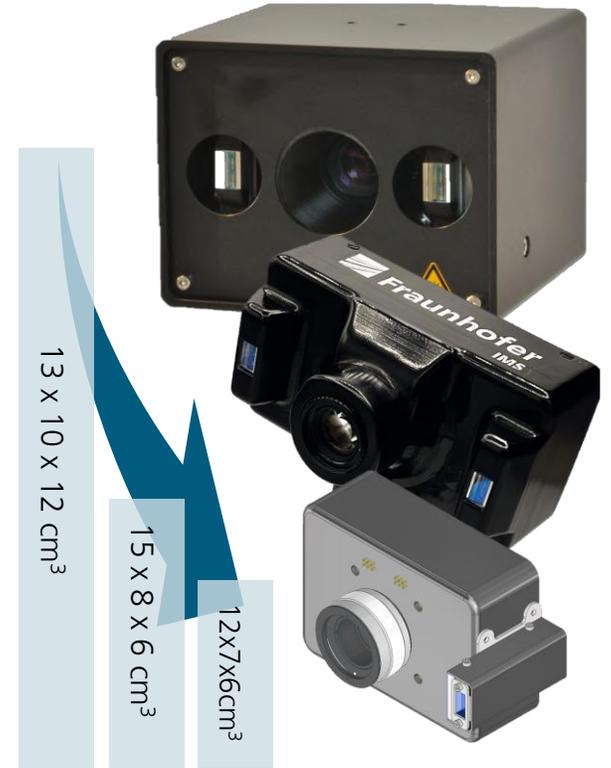
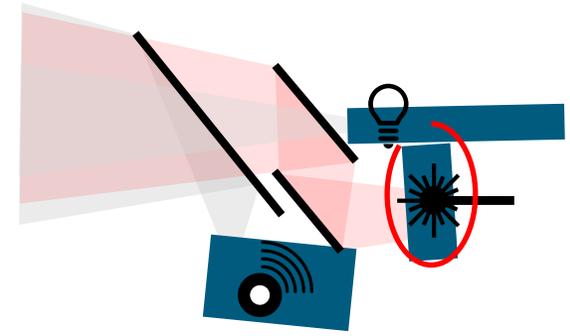
+ photon-based true random number generator simultaneous to distance measurement

+ Data rate for random number generation

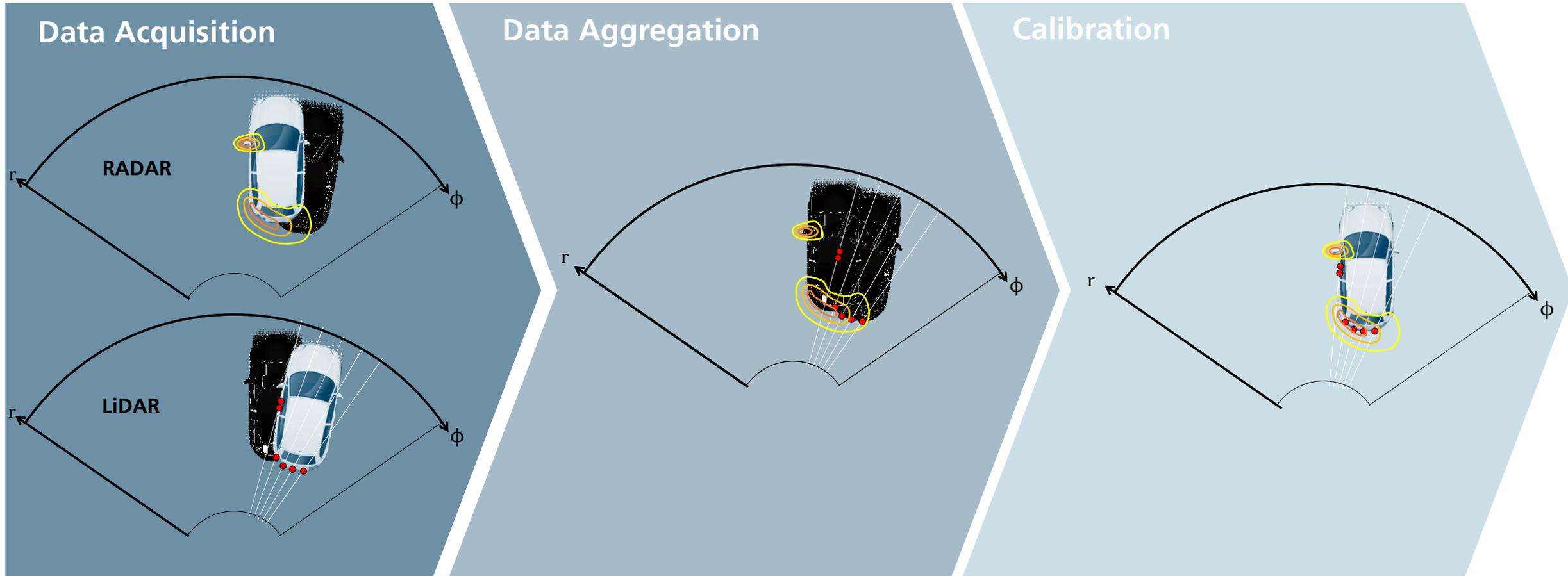
10⁵ bit/s



Size Reduction



Data Fusion of LiDAR and RADAR in Smart Headlight



Smart Headlight

Take Away



Light

- + Maskless micro-optical beam shaping
- + ECE conformal low beam
- + Switchable segmented high beam
- + Size reduction



LiDAR

- + ~15 fps → 144 fps
- + 0.5 % memory consumption compared to state of the art
- + 10^5 bit/s random number generation for encoded signal



Radar

- + Optical transparent Radar reflector demonstrated successfully
- + Patterned reflector induces 15% range loss in favor of increased transmissivity

Smart Head-Light

Thank you for your interest

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