LiangDao

A location independent LiDAR-based real-time approach for validation of lane keeping assistance and lane departure warning system

Software Engineer | LiangDao GmbH | Berlin

ABOUT LiangDao

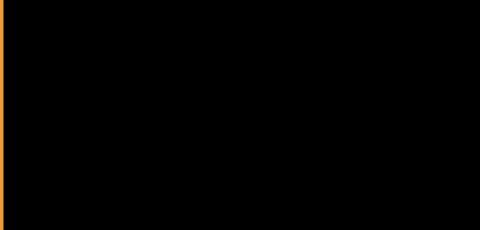




LKA and LDW

- LKS: Lane Keeping Assistant
- LDW: Lane Departure Warning





source

Source: Mercedes-Benz



Conventional approaches



Visual observation and record - labor-intensive; rough



HD map

- not always updated and prior knowledge is needed



GNSS and RTK

- expensive; limited by the testing field ; too much preliminary work



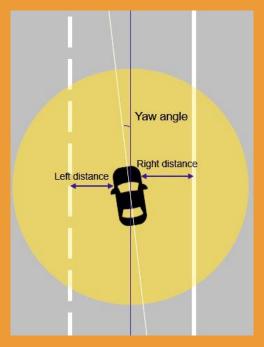
An example: Testing and validation of LKA and LDW using GNSS and RTK



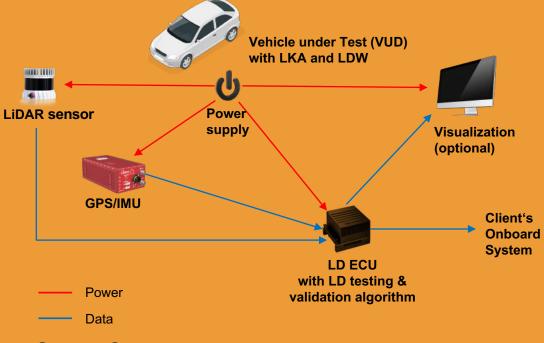
Expensive, time consuming and only in limited testing areas



LiDAR based method: flexible, open road and cost efficient



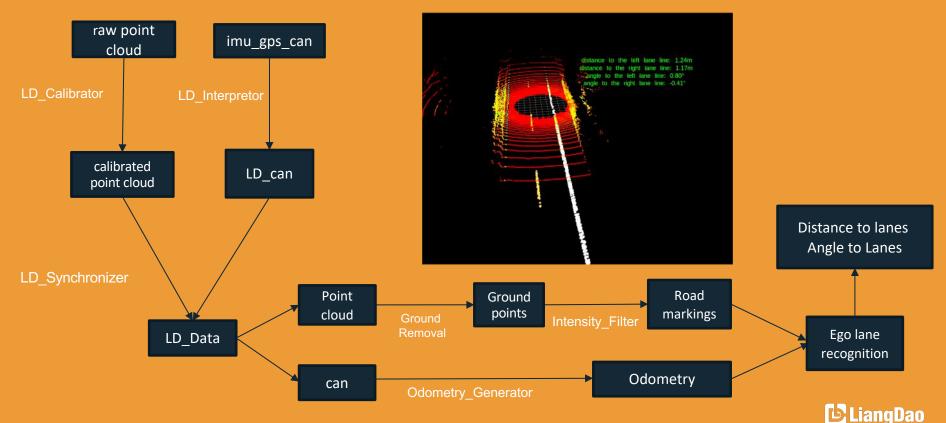
Technical Parameters detected by LiDAR sensor in real-time



System Components

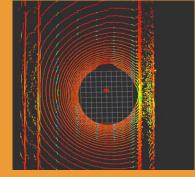


LiDAR data processing workflow



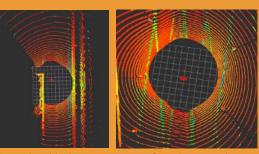
How to deal with different road conditions? Confidence level concept

Best case:



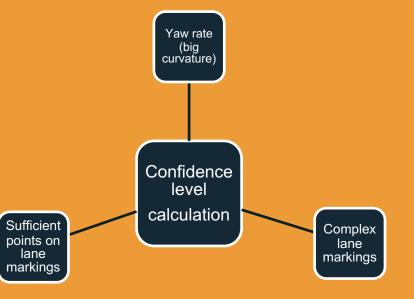
Straight road with clear road markings

Worst case:



Long-time blockage

Complex or unclear lane markings

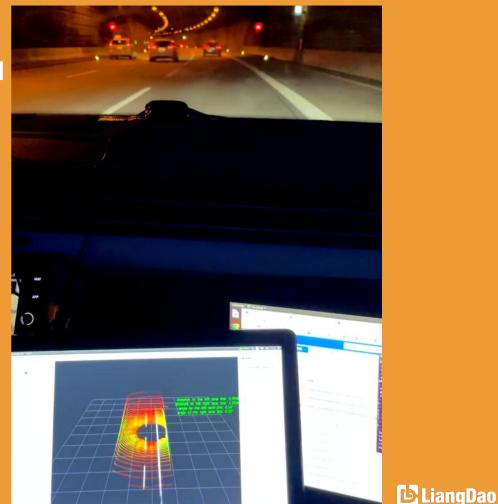




Self-Testing On LiangDao Reference Vehicle on open road

The result can be acquired in real-time with visualization tool.

> With our LiDAR-based system, the testing can be done on any public road with road markings day and night.









Advantages

- 1. Flexible application for open road
- 2. Easy-to-use system design
- 3. Accurate result with confident level
- 4. Real time testing result
- 5. Cost efficient



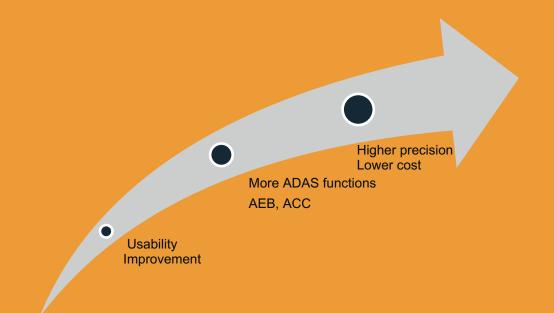
Reference Project: Magna Steyr







Future work





THANK YOU!

Do you have any questions? Visit our booth outside

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