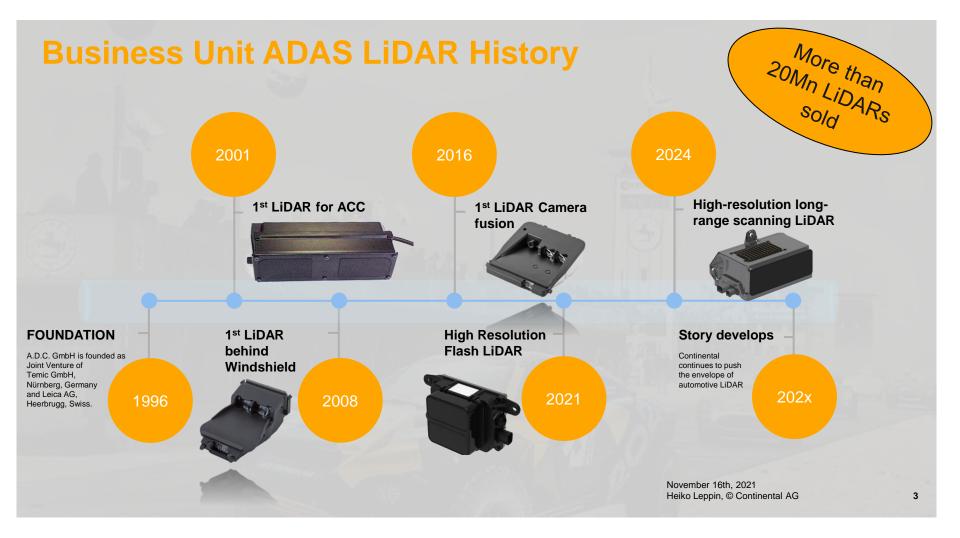


High-Performance, Agile LiDAR for Flexible Integration DVN LiDAR Conference, 15.-16.11.2021





LiDAR – Required for Safe Automated Driving Full Range Portfolio

Short Range LiDAR



Solid State Flash LiDAR

Highlights

- > No gaps in image/data. No motion distortion
- > High accuracy object and free space detection
- In production with premium Japanese OEM

Target application:

Urban areas, traffic jam, robocabs





Long Range LiDAR

Strategic investment in LiDAR pioneer



MEMS¹ Mirror Scanning LiDAR

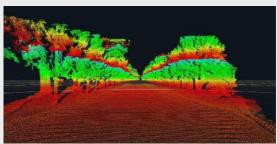
Highlights

1 MEMS: Micro electro-mechanical system

- > Patented novel advanced MEMS¹ technology
- Dynamic spatial resolution enabling concurrent far range, high resolution and high sensitivity at minimized power consumption

Target application: Highway

Target SOP: 2024



LiDAR – Focus on integration based on Use Case(s)

- > With high-performance / agility being fulfilled, the focus turns to integration
- > Continental has established a portfolio of high-performance LiDAR sensors
 - Implementation based upon customer / OEM preferences
 - **Possible vehicle integration locations:**
 - Grille
 - Roof
 - Headlamp
 - > Windshield



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HRL131 Base Design

Modular building blocks and SW configurability

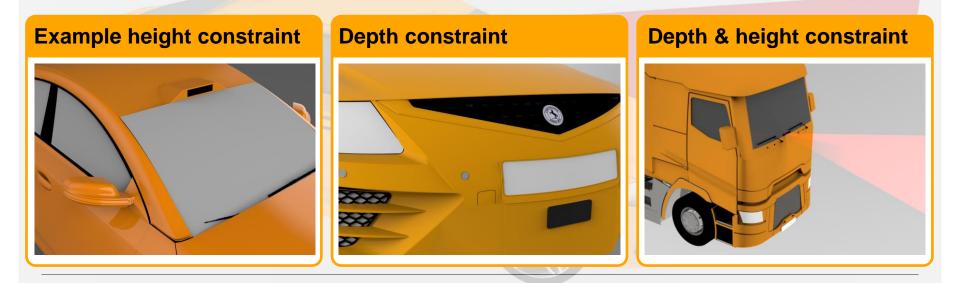
- Core sensor components based on A∈Y∈ technology
- Designed for maximum flexibility
 - Opto-mechanical components can be re-arranged for optimized packaging or other constraints
 - Single laser emitter (scan block) can be used with multiple receivers (FPAs)
 - Programmable Fields of View (static or dynamic)
- > Continental offer wide performance in a variety of packaging form factors



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HRL131 - Opto-mechanical Configurations

- > Standardized opto-mechanical components
- > Components can be re-arranged to fit mounting space
- > Re-arrangement does not affect performance

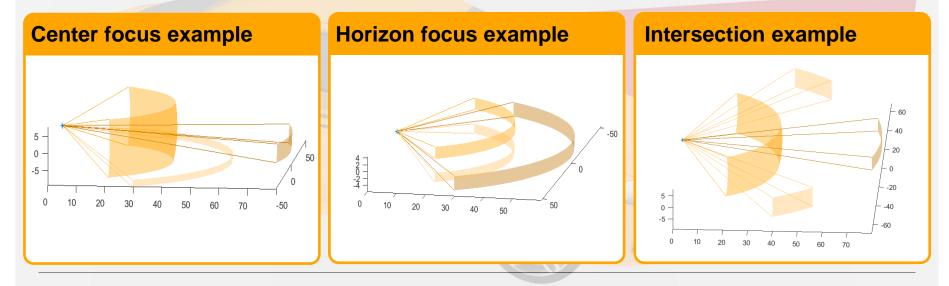


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HRL131 – Programmable Sensing Area

- > Sensor receiver(s) establish Field(s) of View envelope
- > Transmit unit defines Field of View shape and pixel density
- > One transmit unit can support multiple receive units

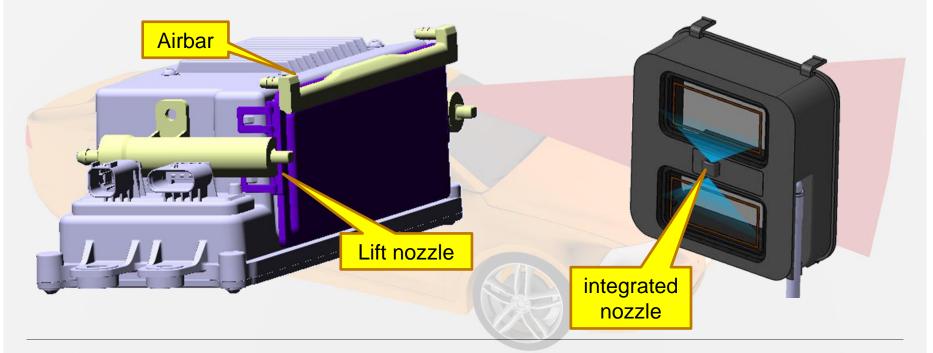


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Cleaning:

Optical sensors require cleaning no matter where they are located



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Example of LiDAR cleaning system



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Windshield Location

Integration remains challenging

- > Continental has long experience with windshield integration
- > The presented modular design can enable in-cabin integration
- Windshield losses make performance unattractive for certain passenger car integrations
 - High Fresnel losses (typ. incident angles 65°-80°)
 - Coating endurance (no resistance to wiper and ice scraper)
 - > Platform dependency (angle depends on vehicle platform)
- > For steep windshields, this is a preferred integration option for OEMs





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High-Performance, Agile LiDAR for Flexible Integration Thank you for your attention.



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