

## NCAP ROADMAPS REGARDING THE ASSESSMENT OF **ACCIDENT AVOIDANCE SYSTEMS**

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## **Outline**



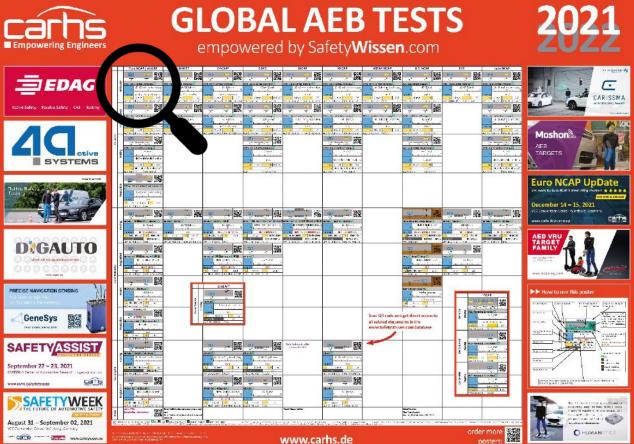
- Current status
- Roadmaps
- General trends

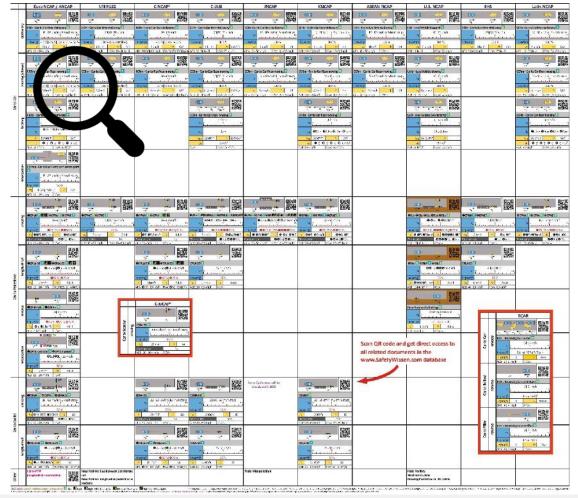
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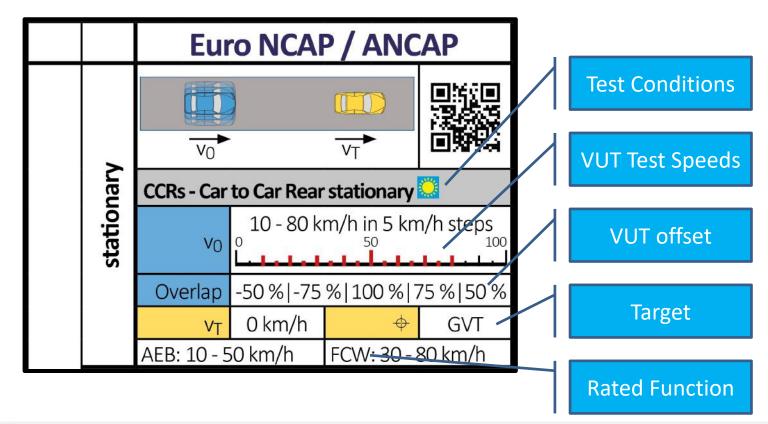






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	stationary	10 - 80 lam√h in 5 km steps p 50 (30)	20 42 60 km/h vp 0 90 120	20 - 80 km/h Va 9 50 1.00	30 50 72 km/h Vo 0 50 KC	10 - 60 km/h in 5 km/h steps 0 50 80	10 - 50 km/h in 5 km/h steps 3 50 100	10 - 60 km/h in 5
	569	Overlap <1.75 %11 ×150 %	Overlap 100 % (±0.2 m offset)	Overlap -50 %   100 %   +50 %	Overlap 100%	Overlap 100 %	Overlap 100 %	Overlap 100 5
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	_	AEB: 10 - 50 km/h FCW: 30 - 80	EB: 10 - 60 km/h FCW: 10 - 60 km/h	AEB: 20   30   40 km/h   FCW: 50   60   70   80 km/h		AEB: 10 - 60 km/h FCW: 10 - 60 km/h	12 22 - 1 - 2	AEB: 10-60 km/h FCW:-
	ver)	Vot VT						V0 V1
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	moving (s	30 - 80 km/h in 5 km/h steps 0 30 - 80 km/h steps	30 60 km/h 19 19 120	30 - 80 km/h u 50 120	50 70 72 km/h 0 58 100	35 - 60 km/h in 5 km/h steps ο 1α	30 - 70 km/h	30 - 60 km/h in 3 9 50
	Ē	Overlap  -50 % -75 % 100 % 75 % 50 %	Overlap 100 % (±0.2 m offset)	Overlap -50 %   100 %   +50 %	Overlap 100 %	Overlap 100 %	Overlap 100 %	Overlap 100 5
		v⊤ 20 km/h + GVT	ν <sub>T</sub> 20 km/h → ISO-	v <sub>T</sub> 20 km/h	v <sub>T</sub> 20 32km/h → EVT/GVT	v₁ 20 km/h + EVT	v₁ 20 km/h² + EVT	ν <sub>T</sub> 20 km/h
à	$\vdash$		AEB: 10 - 60 km/h FCW: 10 - 60 km/h	AEB: 30 40 50 km/h   FCW: 60 70 80 km/h		AEB: 35 - 60 km/h FCW: 35 - 60 km/h		AEB: 30 - 60 km/h FCW: -
CartoCar		v <sub>0</sub> d <sub>0</sub> v <sub>T0</sub> a <sub>T</sub>			ν <sub>0</sub> d <sub>0</sub> ν <sub>τ0</sub> a <sub>τ</sub>		v <sub>0</sub> d <sub>0</sub> v <sub>T0</sub> , a <sub>T</sub>	
	100	CCRb - Car to Car Rear braking			CCRb - Car to Car Rear braking		CCRb - Car to Car Rear braking	
	braking	50 km/h 90 90 90 90 90 90 90 90 90 90 90 90 90			72 km/h Vo 0 100		50 km/h 3 50 100 101 101 101 101 101 101 101 101 10	
	-	do 012 m 040 m 012 m 040			d <sub>0</sub> 30 m	l	do 012 m 040 m 012 m 040 m	
		v <sub>10</sub> 50 km/h			Vig 72 km/h 6 EVT/GVT	1	v <sub>im</sub> 50 km/h	
		at 0-2 9-2 6-6 0-6 m/s <sup>2</sup>			ат -3 m/s²	1	at 0-2 0-2 0-6 0-6 m/s²	
	ш	AEB: 50 km/h FCW: 50 km/h			AEB:- FCW: 72 km/h		AEB: 50 km/h FCW: 50 km/h	
	5	CCFtap - Car to Car Front turn across path						
	intersection	10 - 20 km/h in 5 km/h steps						
	Ē	impact@ 50 %  vt 30[45]55 km/h						
		AEB: 10 - 20 km/h FCW:-						40
raini	000	m h h						6





# Current Status Car to Car



	Euro NCAP	C-NCAP	C-IASI	JNCAP	KNCAP	ASEAN NCAP	U.S. NCAP	IIHS	Latin NCAP
stationary	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>✓</b>
moving	✓	✓	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>		<b>√</b>
braking	<b>√</b>		<b>√</b>		<b>√</b>		<b>√</b>		<b>√</b>
intersection	<b>√</b>								

# Current Status Car to Pedestrian



1	Euro NCAP	C-NCAP	C-IASI	JNCAP	KNCAP	ASEAN NCAP	U.S. NCAP	IIHS	Latin NCAP
crossing	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>			<b>√</b>	<b>✓</b>
longitudinal	<b>√</b>	✓	<b>√</b>					<b>√</b>	
reverse	✓								
intersection	<b>√</b>								

# Current Status Car to Cyclist



00	Euro NCAP	C-NCAP	C-IASI	JNCAP	KNCAP	ASEAN NCAP	U.S. NCAP	IIHS	Latin NCAP
crossing	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>	<b>√</b>			<b>√</b>	<b>✓</b>
longitudinal	<b>√</b>	✓	<b>√</b>					<b>√</b>	

## Current Status Car to Powered Two Wheeler



	Euro NCAP	C-NCAP	C-IASI	JNCAP	KNCAP	ASEAN NCAP	U.S. NCAP	IIHS	Latin NCAP
crossing		$\checkmark$							

## **Outline**

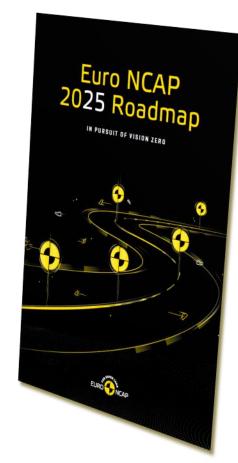


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Roadmaps

## **Euro NCAP**

Current Road Map 2025



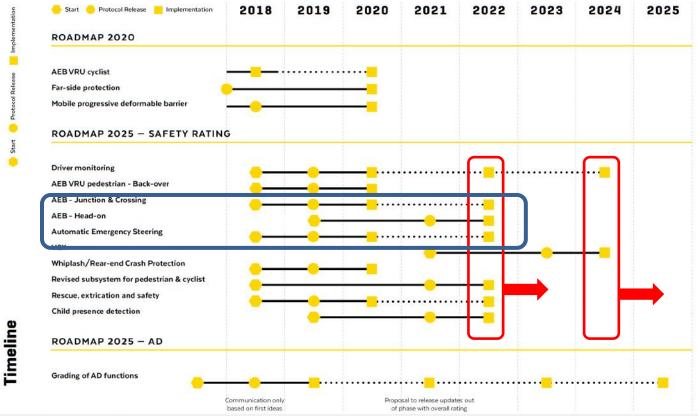


https://bit.ly/3jkYnwi

#### Roadmaps

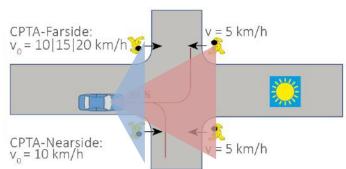
## **Euro NCAP**



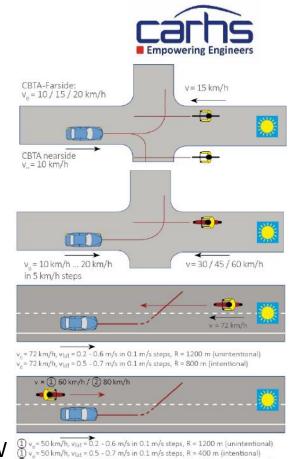




- New 2023 AEB requirements
  - AEB Car to Car: under discussion
    - Crossing (nearside & farside)
    - Head-on (overtake & drift)
  - AEB Car to Pedestrian: published
    - Crossing, far side adult and obstructed child now also tested at night
    - Intersection turn across path pedestrian in same direction added
    - Scores for night scenarios increased
    - Scores for daylight scenarios decreased



- New 2023 AEB requirements
  - AEB Car to Cyclist: published
    - Intersection turn across path scenario added
    - Dooring added
    - New scenarios get 1/3 of the points
  - AEB/LSS Car to PTW: published
    - Stationary PTW
    - Braking PTW
    - Intersection turn across path oncoming
    - Emergency Lane Keeping oncoming/overtaking PTW



 $v_n$  = 72 km/h,  $v_{lat}$  = 0.2 - 0.6 m/s in 0.1 m/s steps, R = 1200 m (unintentional)  $v_n$  = 72 km/h,  $v_{lat}$  = 0.5 - 0.7 m/s in 0.1 m/s steps, R = 800 m (intentional)



- Road Map 2030
  - Development Process started in 2021
  - Industry consultation in Q1 and Q2 /2022
  - Publication targeted for end of 2022





## **SAFETYUPDATE** Roadmap 2030: Strategic Drivers

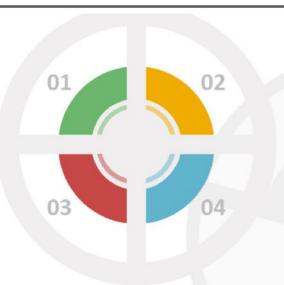


#### **Technology Innovation**

- · Connected and automated vehicles: from assisted to autonomous driving
- · Next generation ADAS including driver monitoring systems
- · Over-the-air update of safety functions



- Deployment of virtual testing
- Improved accuracy of test hardware and software
- Rating methodology include (assisted or automated) driving and improve real-world impact



#### Societal Trends

- · Changing demography aging population, impairment, gender
- · Mobility as a Service, car ownership
- · Fatal and serious injuries VRU. passenger cars and heavy goods, impact of automation
- · New energy vehicle safety
- · Regulatory framework & international cooperation

#### Horizontal Growth

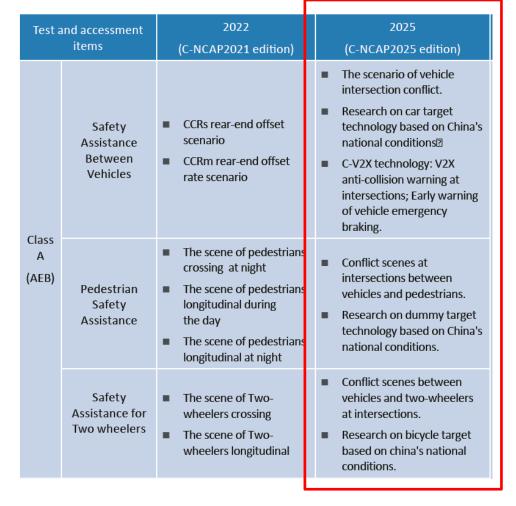
- Commercial vehicles
- Safety accreditation for autonomous vehicles
- · PTW safety: helmets, personal protection equipment
- Micro-mobility safety guidelines



Director and Professor Andre Seeck - BASt | © 2021 carbs training gmbh



## Roadmaps **C-NCAP**





# Roadmaps **C-IASI**



Cub inder	December Brodest	2023 Version						
Sub-index	Research Project	2021	2022	2023	2024			
Damageability and Repairability	- Frontal low-speed structure collision, rear-end low- speed strucutre collision - Full-width bumper frontal collision, full-width bumper rear-end collision - Bumper static test							
Vehicle Occupant Safety	- Small Overlap Frontal Crash (evaluation of female dummy in the back row) - Side impact crash (new barrier, remote occupant protection) - Frontal 50% offset deformable barrier crash (MPDB evaluation) - Seat/Head restraint (high-intensity wave, rear seat) - Roof strength - Emergency rescue service (E-call) - Overall rating adjustment	Project rating plan	Regulations draft for solicitation of comments	Officially released	Officially implemented			
Pedestrian Safety	- Pedestrain protection, two-wheeled vehicle protection - Automatic emergency braking-car to pedestrian and cyclist (CVRU)							
Vehicle Assistant Safety	- Automatic emergency braking-car to car (C2C), AEB intersection  - Lane departure assist (LDW+LDP), emergency lane keeping (ELK), emergency automatic steering (AES/ESS)  - Headlight evaluation  - Driver monitoring (DMS)  - Smart key							

## Roadmaps **IIHS**



- Significant changes targeted for 2023
  - A revised front crash prevention evaluation to include pedestrian autonomous emergency braking tests in low-light conditions.
- Possible changes for 2023 and later
  - A revised front crash prevention test to evaluate additional vehicle-tovehicle impact configurations beyond colinear front-rear alignment with full overlap.

Source: IIHS TSP Letter 2022, Feb. 1, 2021

# Roadmaps **KNCAP**



			2020	2021	2022	2023	2024	2025
	Rollover	Abolish SSF and Roll-over		Phase out				
	Braking	Abolish	Phase out					
	FCWS	Assess AEBS Function	Phase out					
	LDWS	Assess LKAS Function	Phase out					
Accident	LKAS	In conjunction with LDWS			Imple	ement		
Prevention		In conjunction with FCWS Cyclist , Night AEB added			Imple	ement		
[20]	AEBS	New scenarios (Interurban, City, Pedestrian)				Imple	ement	
		Cross-Junction, Offset, Reverse						Implement
	ACC	Abolish as convenient devices	Phase out					
	RCTA	Add Active Function to RCTA(Stand)			Impl	ement		
	ESF	New			5 2	Imple	ement	

## Roadmaps **JNCAP**

### **AEB**





			<u>/</u>					177			
				2019年度	2020年度	2021年度	2022年度	2023年度	2024年度	2025年度~	
	予防・御	历实等総合安全性制	B	普及方策の検討							
			対車両	基準化を見据えた 試験・評価方法検討 基準化を見据えた	試験・評価方法の再検証 注)国産車2021年11月						
			対参行者(昼間)	試験·評価方法检討	(生/国座率2021年11月)						
	予	被害軽減ブレーキ	対赤行者(夜間・御灯あり)				2018年度~ 2019年度~				
	100		対参行者(夜間・街灯なし) 対自転車	試験·評価方法検討	98 (m. +-0) +6 (s.) / m. (m. e) +6 (s.)	予備試験	7013十段。				
	防	1		必然"計画力伝传的	評価方法検討/予備試験		al / w. Michiga		Til.		
	安	交差点			調查·研究	試験·評価方法檢	Pathal Wateran	予備試験			
	全	高機能走行用前照灯			2018年度~						
		ベダル踏み間違い時加速抑制装置		2018年度~	試験·評価	方法再検討					
ょ	性	車両後方視界情報	<b>聚提供装置</b>			(1	2015年度~				
9	能	車線送附警報装置	世·車線逸脱抑制装置			車線逸脱警報装置は2014年	度、車線选脱抑制装置	は2017年度~			
安全な自	評	その他運転支援技術(被害軽減プレーキ[後退 時歩行者]、被害軽減プレーキ[対向車]、V2X 等)				追加新規項目検討 調查·研究 (追加項目)			試験·評価方法検討 (追加項目)	予備試験 (追加項目)	
な自動車の	価	予防安全性能評価全体の総合的な安全性能		普及期の評価方法から 競争期の評価方法への 変更検討	普及期の評価方法から競争 期の評価方法への変更検討 新規項目導入の際の 評価(考え方)の検討			0		<del>)</del>	
普	衝		前 面 (フルラップ)	1996年度~	高齢者を考慮した関値等へ の変更(助手席)	前面(MPDB)と併せて試験・評価法再検討		T \$6.94			
及対	突	İ	前 面 (オフセット)	2000年度~	高齢者を考慮した関値等へ の変更(後席)			TIMET			
策	-	乗員保護	前面 (MPDB(含THORダミー))		調查·研究	試験·評価方法檢討/予備試験 予例	于備試験				
	安		側面				999年度~				
	全		後面頚部保護	試験·評価方法再検討							
	性		助手席・後席 シートベルトリマインダ	試験·評価方法再検討							
	能	歩行者保護	頭部				1003年度~				
		9111H MM	脚 都	201	1年度~	調査・研究 (aPLI)	試験·評価方法検討 (aPLI)	子備試験			
	評価	その他衝突安全技術(スモールオーバラップ、 ボール概要、後突燃料漏れ、後席の頚部保 護、ファーサイド側突等)				追加新規項	目検討	調查·研究 (追加項目)	試験·評価方法検討 (追加項目)	予備試験 (追加項目)	
		衝突安全性能評価	面全体の総合的な安全性能								
	事故後被 客経滅性 能評価	事故自動通報装置		次世代/法規対応 試験・評価方法検討	試験·評価方法変更			調査・研究 (次世代)	試験·評価方法検討 (次世代)	予備試験 (次世代)	
***	CRS安 全性能 評価	前面衝突時安全作	主能			7,2	1001年度~	The state of the s	100		
安全ない音及対策	-	使用性					001年度~				
eam:	啓 発	1			i-size対応CRS等普及方策の	検討					

Source: JNCAP

## Roadmaps **ASEAN NCAP**





specifically tailored to the requirements of the ASEAN population. Depending on the situations and problems that shall emerge in future, larger dummies such as Q6 or Q10 will possibly feature in ASEAN NCAP future crash tests.

#### 8.3 Safety Assist

Come 2026, there is a high possibility that autonomous cars shall begin to populate the roads in Southeast Asia. Singapore, for example, has been making headway for the advent of autonomous driving. Such an interesting development will also mark the arrival of several other devices including the Advanced Driving Assist (ADAS) technology, which by the way is already introduced by several automakers. In addition, ASEAN NCAP anticipates that various technologies such as ESC and AEB will likely become a standard fit in cars. Thus, evaluations as regards these inventions such as AEB for Motorcycle etc., shall possibly be included. Further, the effectiveness of AEB Pedestrian and AEB in poorly lighted areas shall also be put under the microscope to determine whether their application might be considered in our future roadmap, particularly if pedestrian safety emerged as a cause for concern in the ASEAN region.

## Roadmaps Latin NCAP



### **Beyond 2024... towards 2030**

- -Extrication score in AOP assessment
- -Small adult dummy in rear seat (alternating with Q3 or Q1.5)
- -WSID will be used in Pole and MDB.
- -MDB weight of cart increase as well as impact speed increase
- -AEB City will likely be moved from AOP to the SA Box
- -Rear seat whiplash
- -Far side impact (not immediate consideration).
- -Child passenger detection
- -Pedestrian protection subsystems requirements will increase to equal Euro NCAP's
- -AEB VRU will be tested in night scenarios
- -Fittment rates from today's protocols will turn 100% as from 2024.
- -Rear SBR will still be accepted without passenger detection
- -Speed assist will include ISA assessment
- -More AEB, RED and LSS testing scenarios will be included
- -Driver monitoring: "how alert or tired is the driver"
- -Driver monitoring: "Alcohol levels"
- -AEB when the car is moving in reverse mode





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## General Trends Outlook

## Empowering Engineers

- NCAP Programs around the world will add multiple scenarios in the coming years
- Focus on
  - Intersection scenarios requiring larger sensor angles
  - Nighttime scenarios (+ rain, low temperature, ...)
  - VRU scenarios
  - Oncoming scenarios at higher speeds



Source: 4activeSystems

Grid approach: Manufacturer predicts results for all scenarios,
 NCAP verifies prediction in a small sample of scenarios



## THANKS FOR YOUR ATTENTION

Learn more @ www.safetywissen.com and @ www.carhs.de

Connect @ https://www.linkedin.com/in/ralf-reuter/

Get in touch ralf.reuter@carhs.de

### **Abbreviations**



AEB Autonomous Emergency Braking

AES Autonomous Emergency Steering

ELK Emergency Lane Keeping

FCW Foward Collision Warning

GVT Global Vehicle Target

LDP Lane Departure Prevention

LDW Lane Departure Warning

LSS Lane Support Systems

NCAP New Car Assessment Program

PTW Powered Two Wheeler

RED Roadside Detection Systems

VUT Vehicle Under Test