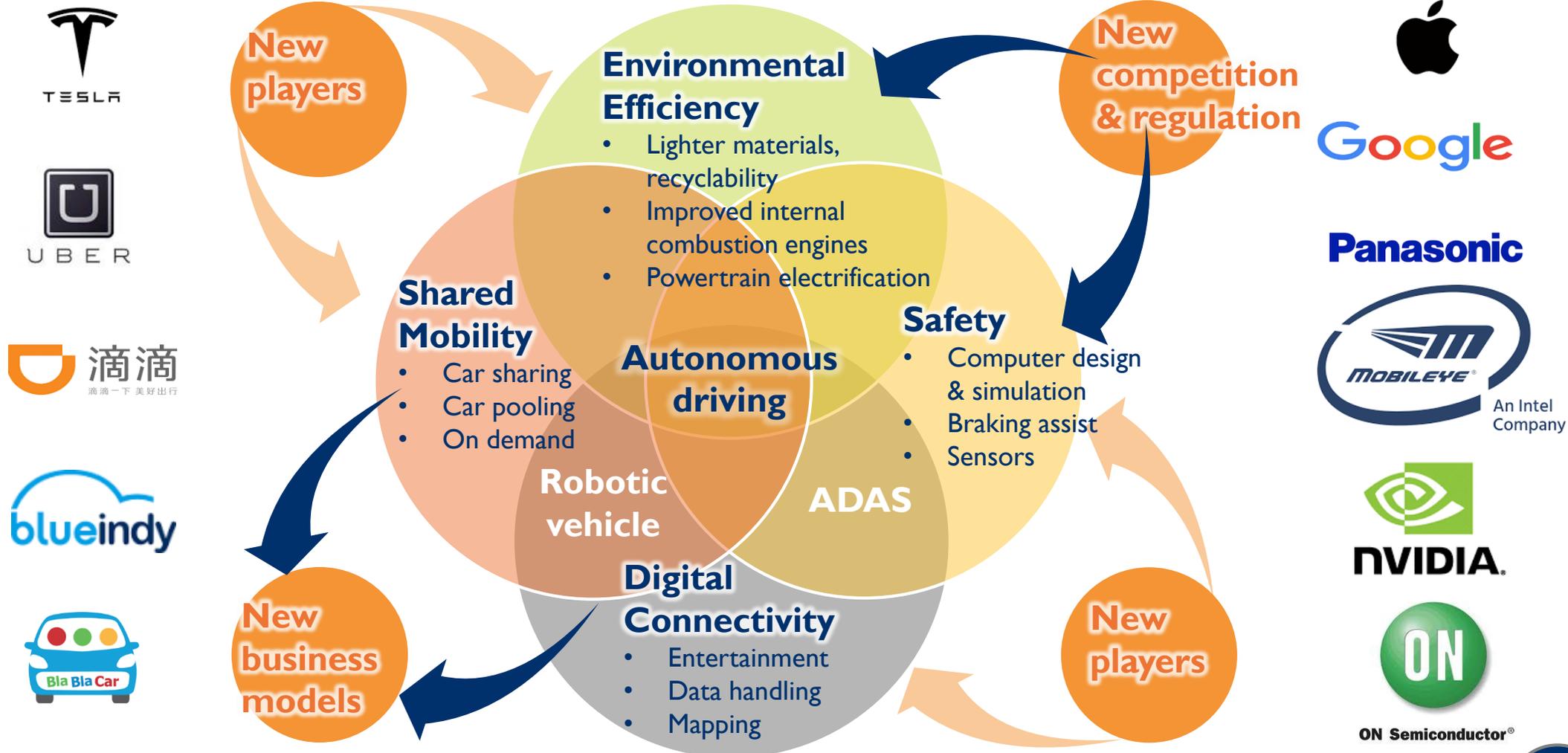


Evolution of the
LiDAR industry
towards driving
automation

AUTOMOTIVE MARKET MACROTRENDS

ADAS and AD are at the intersection of current automotive macro-trends

All trends lead to autonomous driving.

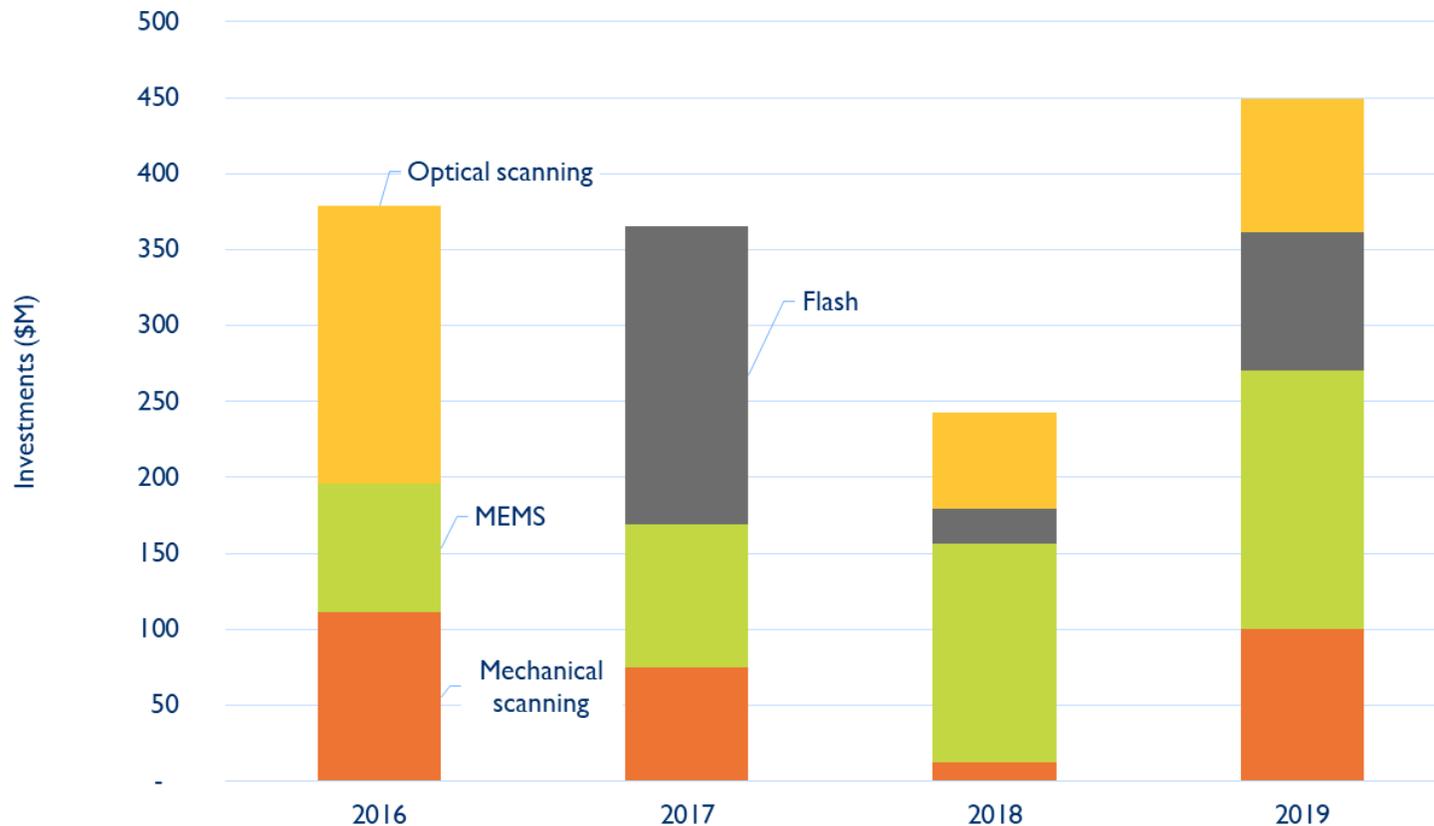


INVESTMENTS IN AUTOMOTIVE LIDAR

Private investments in the LiDAR industry since 2016 – Split by technology

Since 2016, MEMS has been the technology that received the most investment, followed by flash and mechanical scanning.

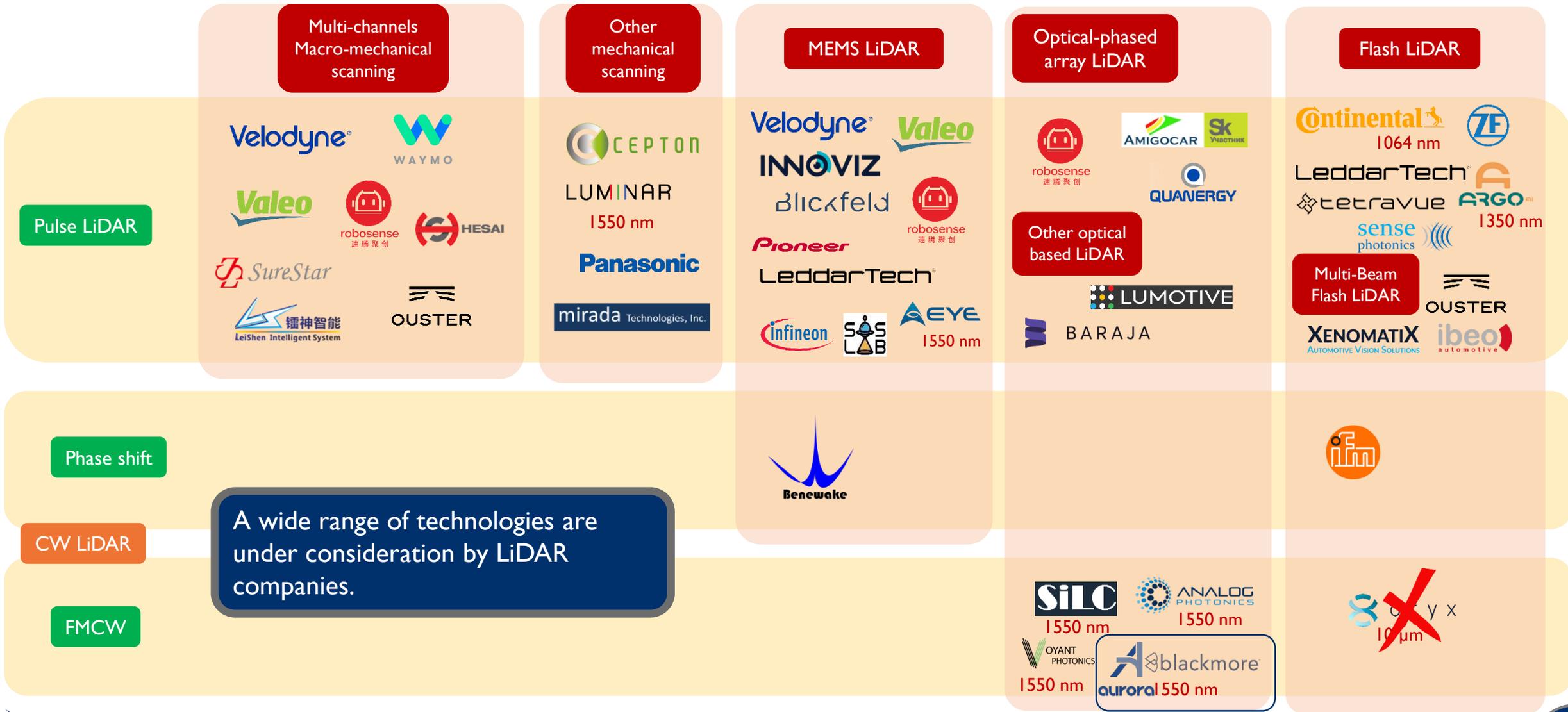
After a slowdown in 2018, investments have reached their highest level in 2019;



Total private investments identified: **\$1,437M**

TOWARDS AUTOMATED DRIVING

Automotive LiDAR player landscape



Except when noted, wavelength is between 830 nm and 940 nm.

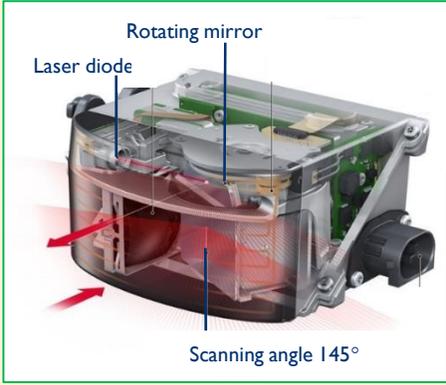
CW: Continuous Wave
FMCW: Frequency Modulated Continuous Wave

TOWARDS AUTOMATED DRIVING

Image formation in LiDAR

From mechanical LiDAR to solid-state LiDAR.

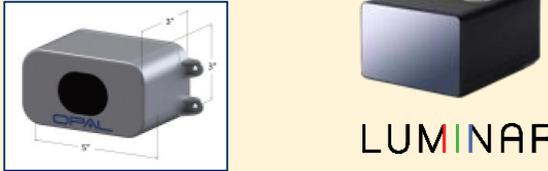
Mechanical LiDAR for ADAS

Mechanical LiDAR for Robotic cars



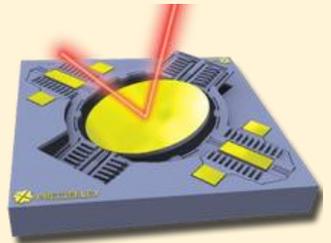

Other mechanical LiDAR

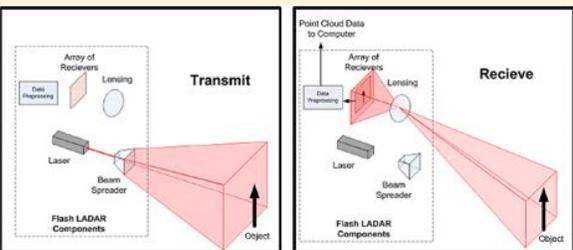
LUMINAR
1550 nm

The present

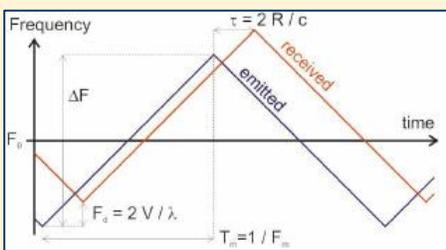
MEMS LiDAR



Flash LiDAR



OPA / FMCW



2020-2021

The future

TOWARDS AUTOMATED DRIVING

Player positioning

More than 50 LiDAR companies

Limited number of OEMs

There are too many LiDAR companies compared to the OEMs willing to implement LiDAR.



TECHNOLOGY UPDATE AND ROADMAP

Potential winner in the next five years?

In the next five years most of available LiDAR should be based on 905nm and use pulse ToF principle.



Credits: Valeo Scala®



Credits: Valeo Scala® Gen2

The second generation will be released by 2020.



Credits: Innoviz

In 2021, BMW will start implementing LiDAR from Innoviz into its vehicles.

Similarities:

905nm EEL

Pulse Time of Flight

Silicon-based sensor

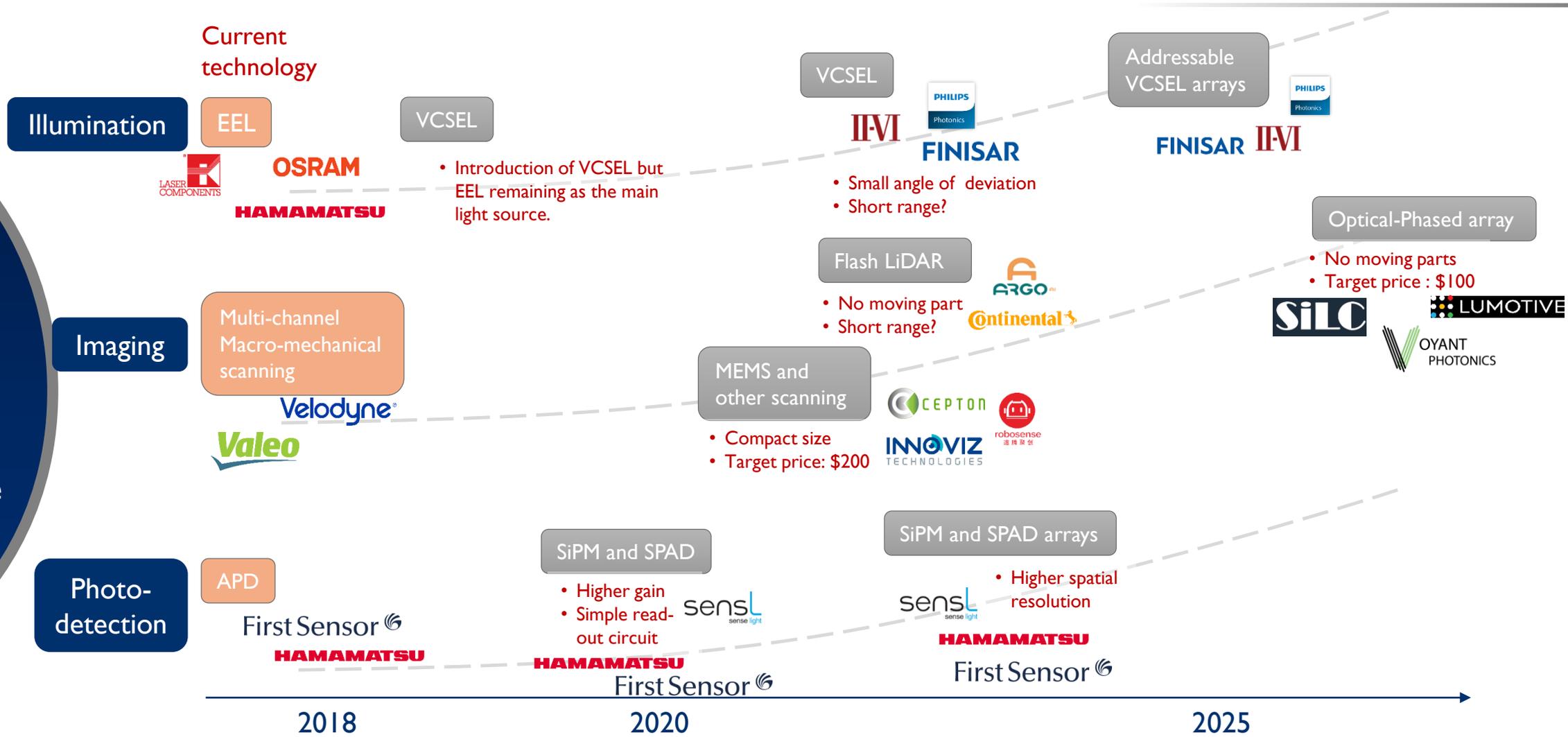


- Most popular ranging method (easiest)
- Lower cost of components

TECHNOLOGY UPDATE AND ROADMAP

How technologies could evolve?

VCSELs and SPADs are expected to become main components.
OPA imaging could emerge at long term.



APD: Avalanche Photodiode
EEL: Edge-Emitting Laser
MEMS: Micro-Electro-Mechanical System
PD: Photodiode

SiPM: Silicon Photomultiplier
SPAD: Single-Photon Avalanche Diode
VCSEL: Vertical Cavity Surface-Emitting Laser

5 years

INTEGRATION OF LIDAR IN ADAS VEHICLE

The difference between robotic and ADAS vehicles

Contrary to robotic vehicles, the integration of sensors in ADAS vehicles is mandatory.

Robotic vehicles



- Level 4/5 of autonomy are targeted
- Plenty of sensors are used to scan the environment: LiDAR (x7) + radar (x7), cameras (x20) for the Ford Fusion example.
- Low/No need to integrate sensors

VS

ADAS vehicles



- Level 3 of autonomy is firstly targeted
- Multiple sensors are used to scan the environment: LiDAR (x1) + radar and cameras
- High need to integrate sensors

INTEGRATION OF LIDAR IN ADAS VEHICLE

LiDAR integration in ADAS vehicles

Integration challenges:

- Aesthetic
- Cleaning
- Heat management
- Optics

Behind the windshield

- Easy cleaning
- Possible obstruction of driver's view

In the grille

- Good position for front LiDAR
- Heat from the engine
- Difficulty of cleaning



In headlights

- Easy integration
- Good for corner (short-range) LiDAR
- Photonic pollution
- Heat management

In bumper

- Easy integration
- Low position \Rightarrow More dirt
- Absence of bumper?
- Difficulty of cleaning

IR Transparent Materials

Image deformation must be avoided.

Ceramic Packaging

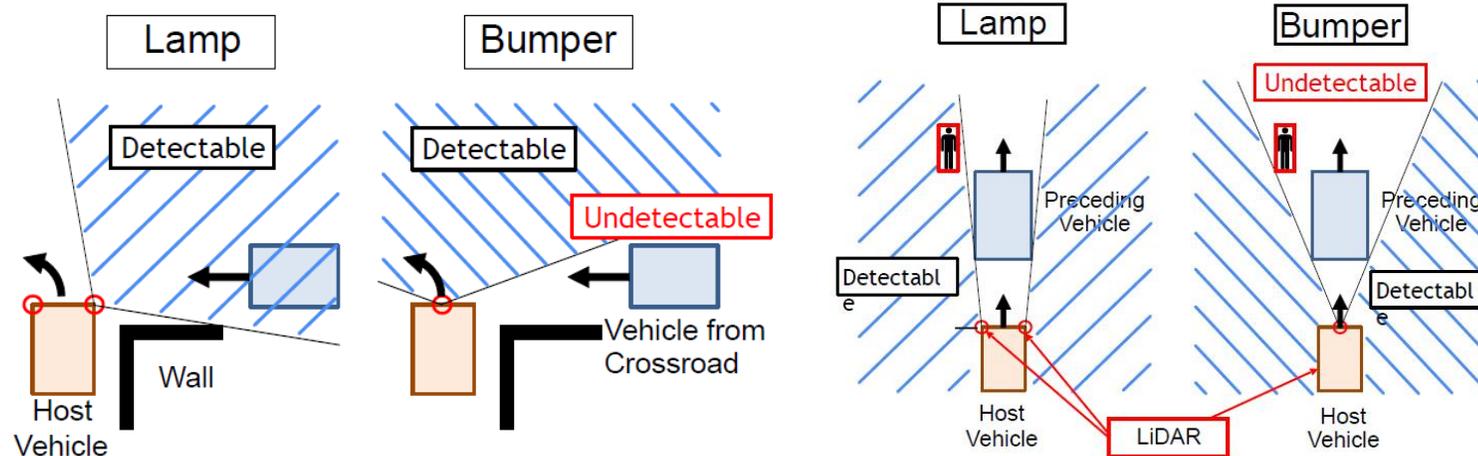
Can be key for heat management

While camera, radar and ultrasonic sensors are already well integrated in the car body, a good position has to be found for LiDAR.

INTEGRATION OF LIDAR IN ADAS VEHICLE

Positioning of LiDAR

Comparison of LiDAR position: headlamp vs bumper



Source: Koito

LiDAR position: behind the windshield



Source: Hella

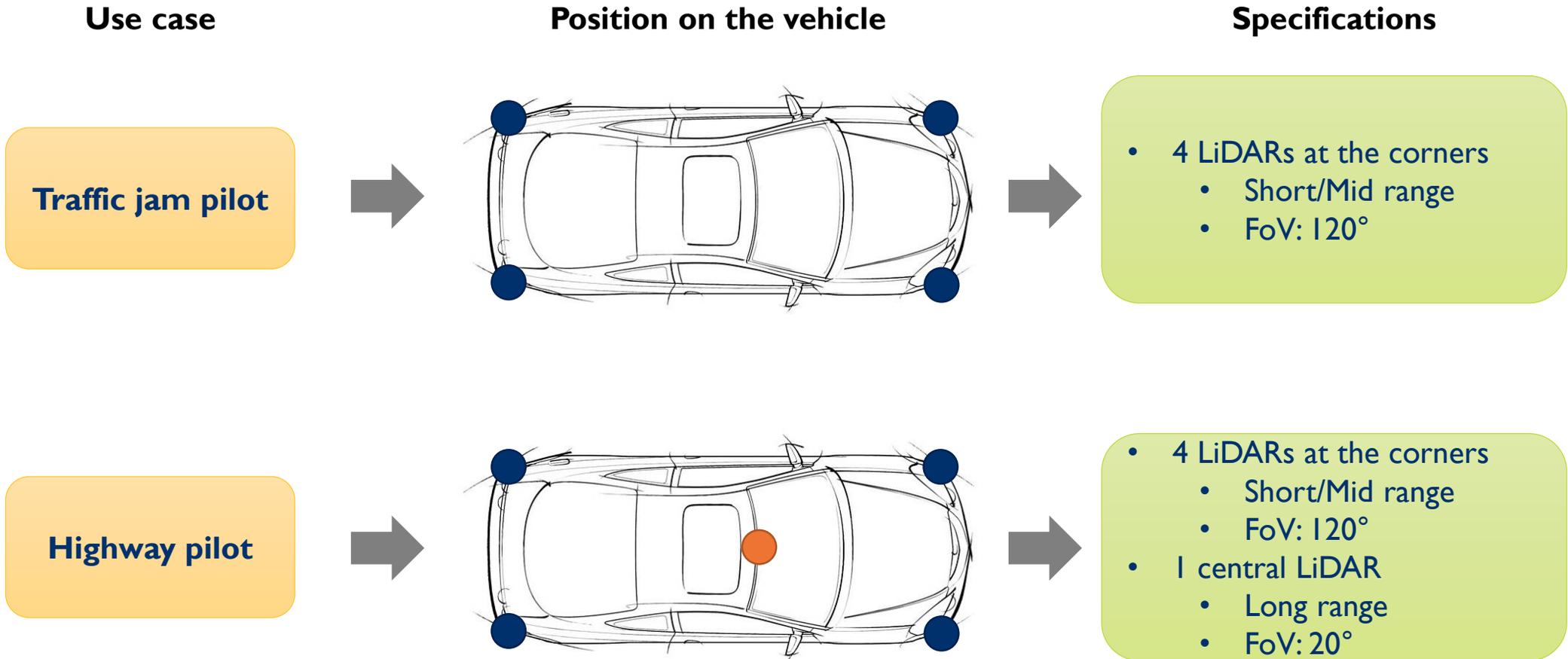
The position of LiDAR in the corners of vehicles seems to have good detection performance in a wide range of cases.

- The LiDAR position in the corners of a vehicle could detect front and rear objects in a wide range of cases.
- Higher position, such as on the roof, would enable to detect objects over surrounding obstructions in some cases. But it would appear difficult to detect a child near the host vehicle.
- There is not one position that fits all use cases but the use case will define the position of the LiDAR(s).

INTEGRATION OF LIDAR IN ADAS VEHICLE

Impact of use case on LiDAR position(s) and specifications (examples)

The use case has a direct impact on the position of the LiDAR(s) and on its specifications.



● Flash or Mechanical or MEMS at 905nm

● Mechanical or MEMS at 905nm (or 1550nm)

INTEGRATION OF LIDAR IN ADAS VEHICLE

Sensor cleaning

Headlamps and sensors have to face severe environmental impacts and conditions. There are various synergies in terms of protection.

Environmental impacts on headlamps and sensors

Ice and snow

Rain

Insects

Dust

Scratches

Stone impact

Temperature

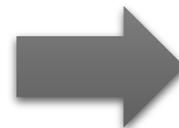
Road condition

Vibration

Moisture

Radiation

Material



Possible solutions

Cleaning

(High pressure, wipers, coatings)

Housing

(Cover lens, Gluing, pressure equalization)

Thermal management

(Active ventilation, heatsink, simulation)

Aiming

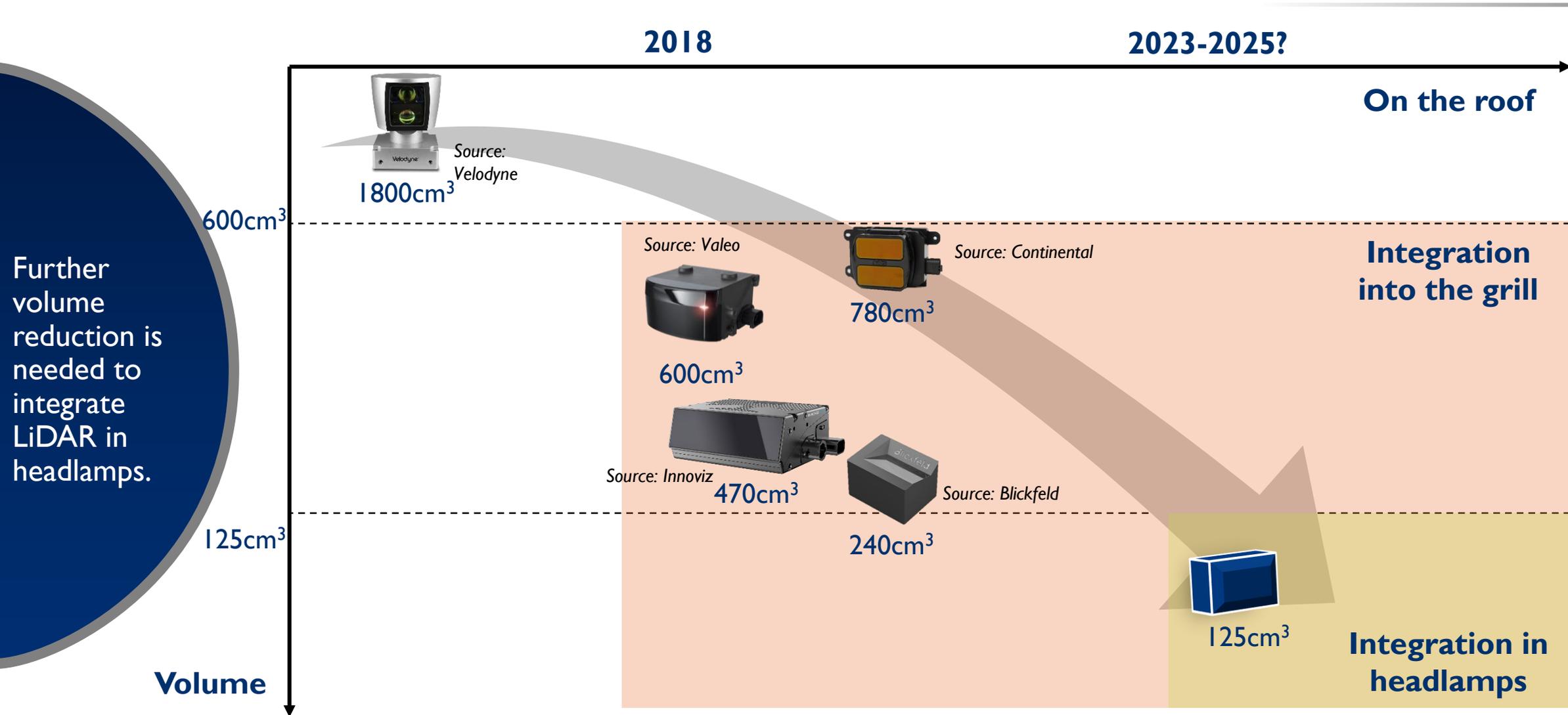
(Levelling actuator, adjustment, levelling sensor)

De-icing / Defrosting

(Wire heated lens, coating)

INTEGRATION OF LIDAR IN ADAS VEHICLE

Size evolution of LiDAR



Further volume reduction is needed to integrate LiDAR in headlamps.

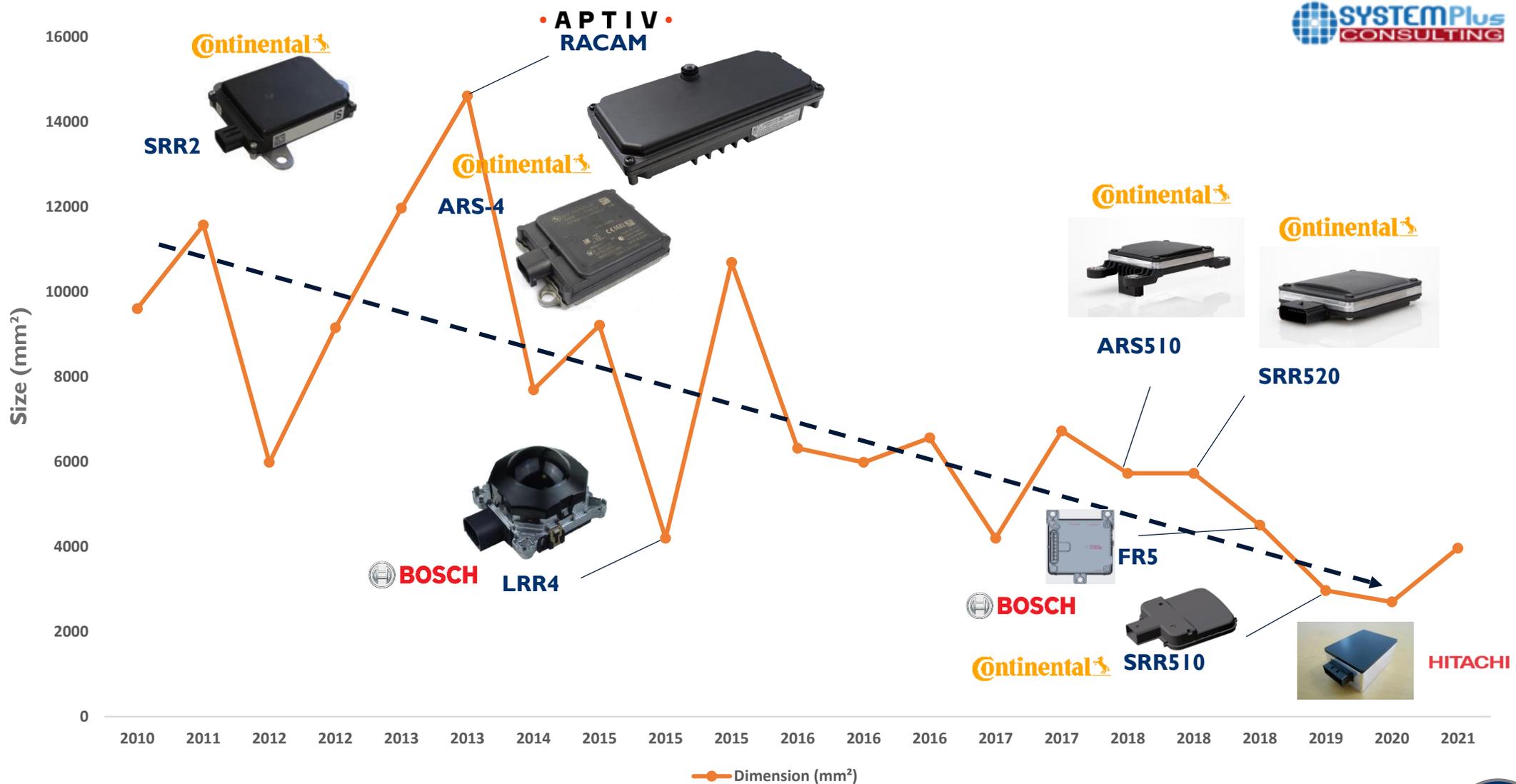
Volume

INTEGRATION OF LIDAR IN ADAS VEHICLE

Comparison with the evolution of radar size

Over the last decade, radar size has shrunk by a factor of 2 - 3, depending on the manufacturer.

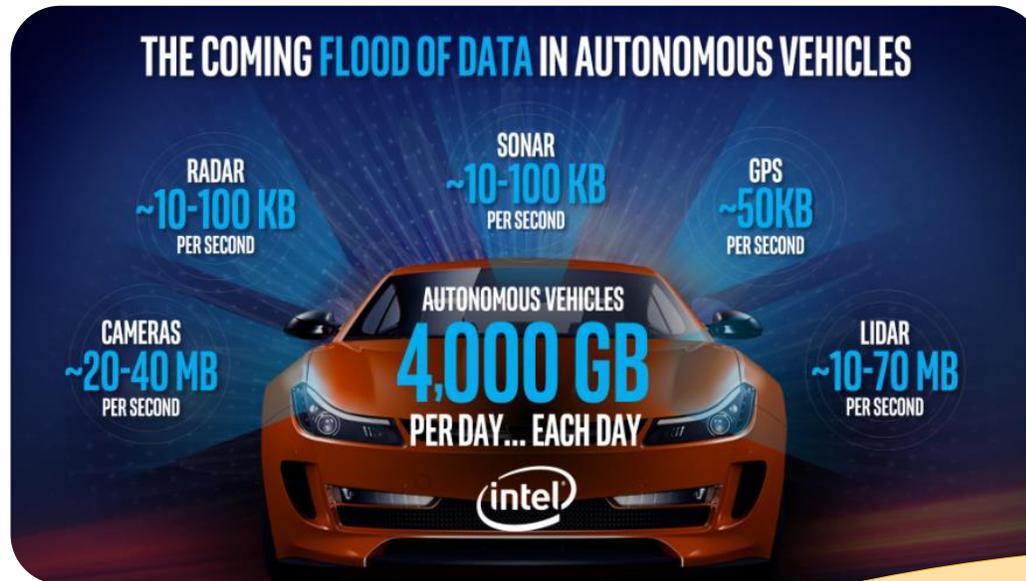
Ford has recently integrated a radar in tail lamps.



INTEGRATION OF LIDAR IN ADAS VEHICLE

Expected developments needed for integration

An increasing number of sensors leading to a huge amount of data to be processed.

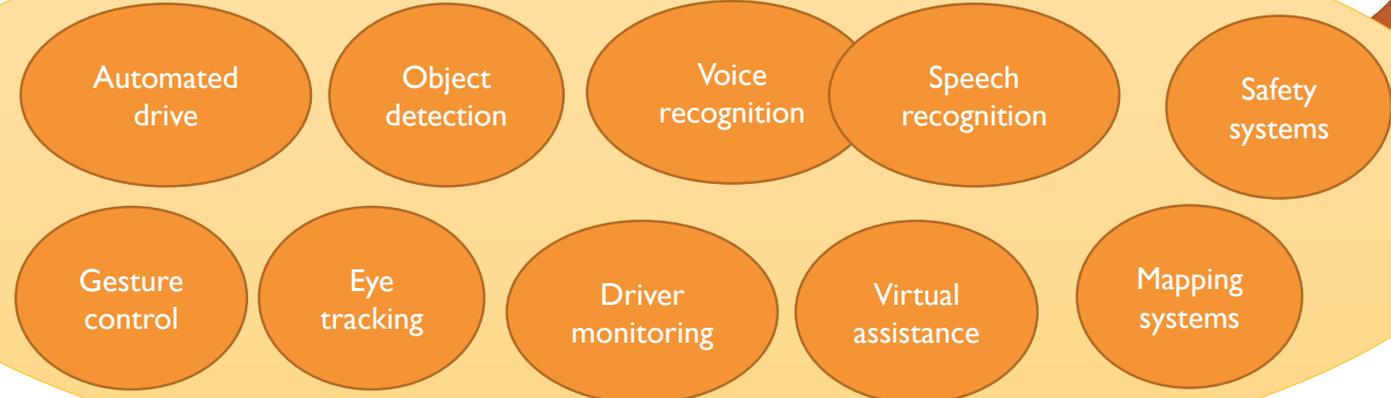


Autonomy

Treatment

AI-based functions in autonomous vehicles

Input



INTEGRATION OF LIDAR IN ADAS VEHICLE

From MCU to fusion platform

Utilization of the existing resources provided by the computing platform used for safety and autonomy.

Intelligence

MIND-OFF



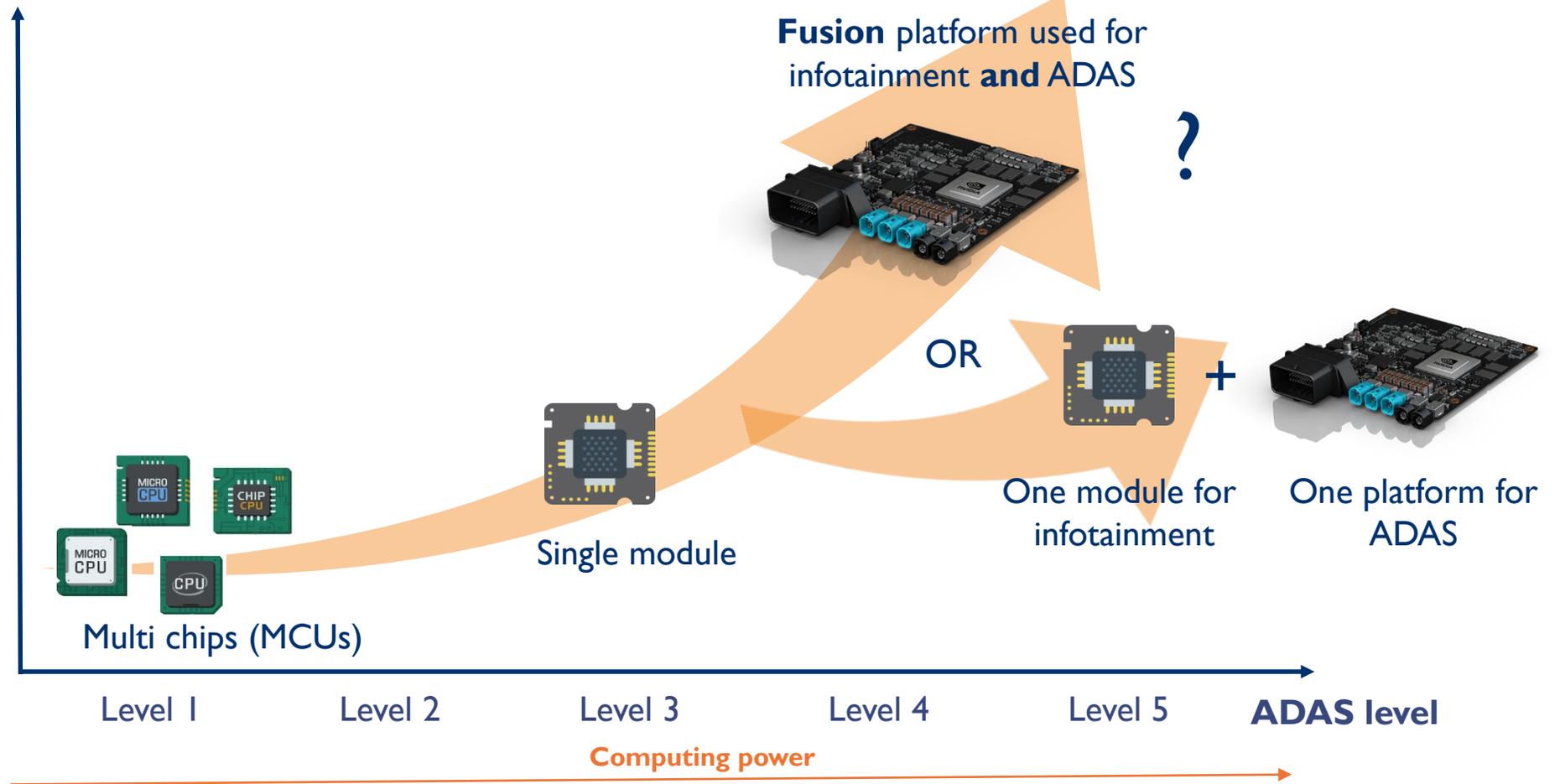
EYES-OFF



HANDS-OFF



FEET-OFF



MAIN CHALLENGES OF DRIVING AUTOMATION



Performance & Safety:

- Under the responsibility of LiDAR manufacturer/tier-1/OEM.
- Make sure that performance meets safety requirements.

Customer trust:

- Will customers trust the vehicle?
- Depends on vehicle behaviour when detecting an obstacle and how it reacts during defined use cases.

Product liabilities:

- Who is responsible in case of accident under automation conditions, the OEM or the driver?
- New insurance models/contracts are needed.



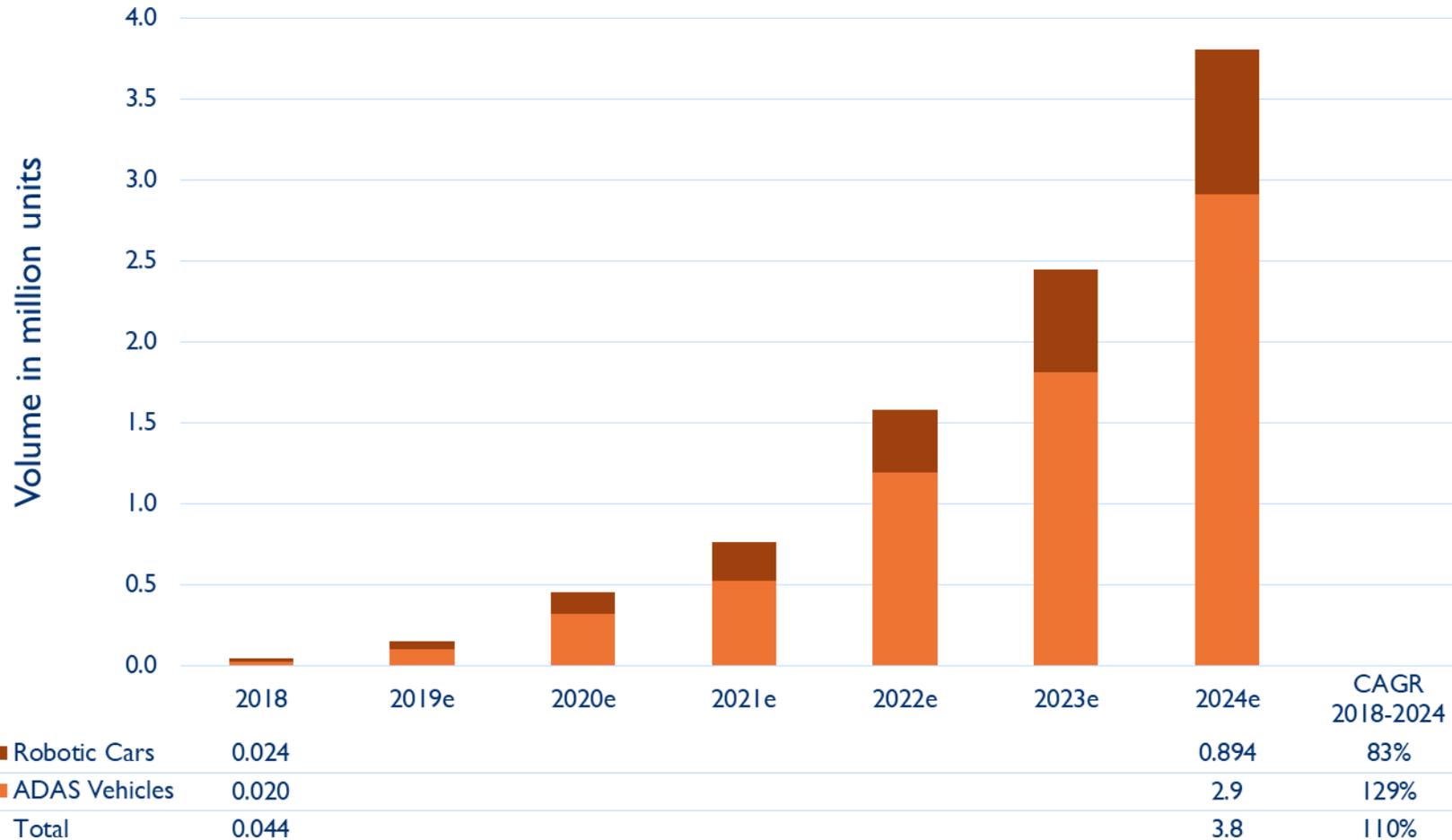
Regulations have to be defined for a large adoption

AUTOMOTIVE LIDAR MARKET

Automotive LiDAR shipment forecast

ADAS vehicles will be responsible for massive LiDAR shipments in the next years.

Automotive LiDAR Shipment Forecast (in million unit)



Note:

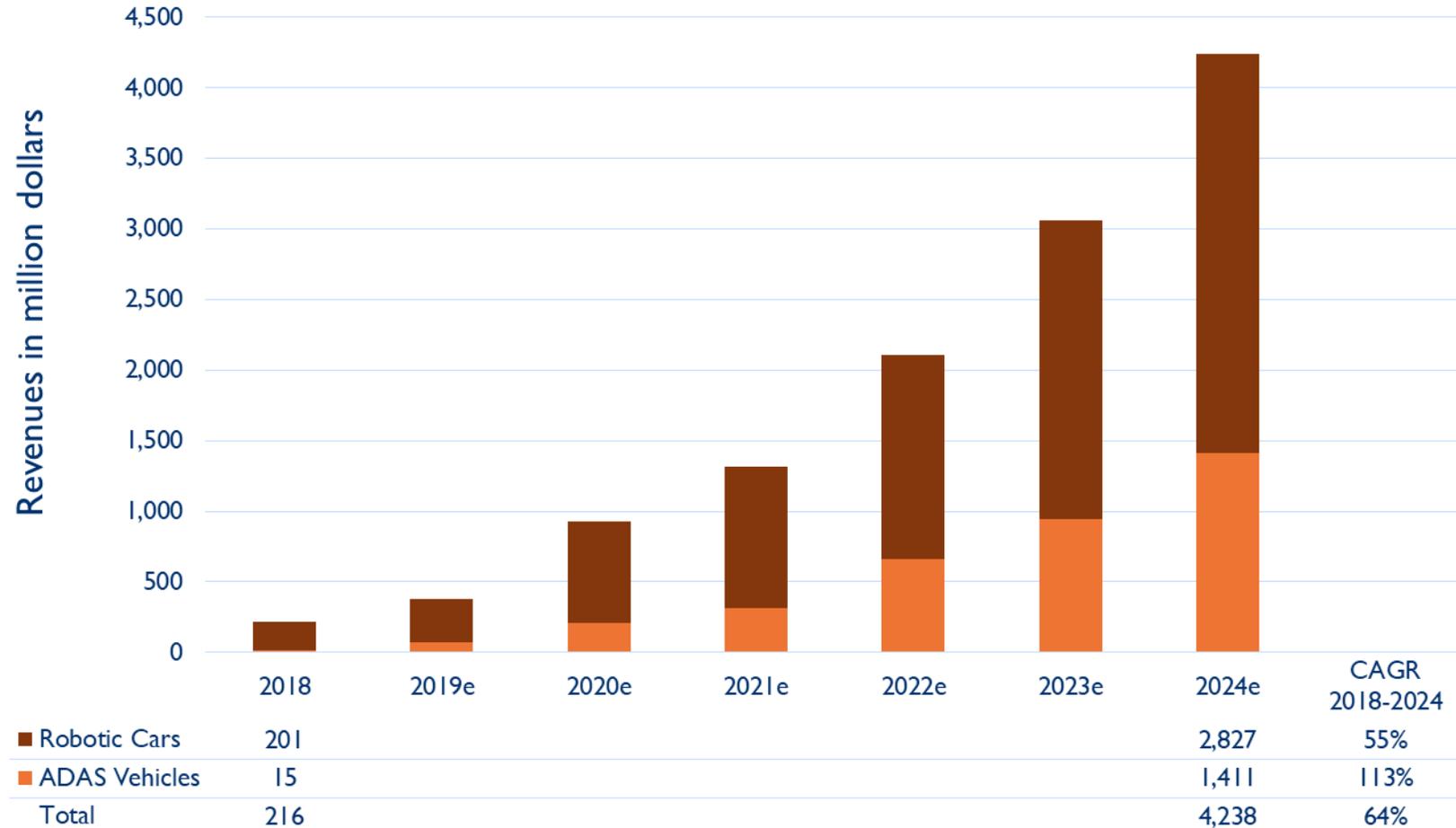
- Robotic vehicles includes cars, trucks, and aircrafts.
- ADAS includes levels 3, 4, 5.

AUTOMOTIVE LIDAR MARKET

Automotive LiDAR market forecast

The LiDAR market forecast is expected to reach \$4.2B in 2024 with LiDAR in robotic vehicles representing two thirds of the revenues.

Automotive LiDAR Market Forecast (in \$M)



Note:

- Robotic vehicles includes cars, trucks, and aircrafts.
- ADAS includes levels 3, 4, 5.

Thank you for
your attention